# Understanding the Origins of Inequality

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Introduction Model Identifying Estimating Conclusion References References

#### Barcelona Talk:

- Sources of Variability in Life Outcomes: (Traits vs. Prices)
  - (a) Uncertainty 50%
  - (b) Predictable traits 50%
  - (c) Predictable traits

## How to Measure Traits:

- 2 Emergence of Traits and Differences
  - (a) Role of Family vs. Genes
- Summarize Evidence on Skill Formation Dynamics
- Role of Parenting Practices Evidence on Family Preferences (Altruism, etc.)



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- An emerging body of research establishes the parallel importance of noncognitive skills, i.e., personality, social and emotional traits.
- Understanding the factors affecting the evolution of cognitive and noncognitive skills is important for understanding how to promote successful lives.

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- We establish identification of general nonlinear factor models that enable us to determine the technology of skill formation.
- Our multistage technology captures different developmental phases in the life cycle of a child.
- We identify and estimate substitution parameters that determine the importance of early parental investment for subsequent lifetime achievement, and the costliness of later remediation if early investment is not undertaken.

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- Cunha and Heckman (2008) estimate a linear dynamic factor model that exploits cross equation restrictions (covariance restrictions) to secure identification of a multistage technology for child investment.
- With enough measurements relative to the number of latent skills and types of investment, it is possible to identify the latent state space dynamics generating the evolution of skills.

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- This paper identifies a more general nonlinear technology by extending linear state space and factor analysis to a nonlinear setting.
- This extension allows us to identify crucial elasticity of substitution parameters governing the trade-off between early and late investments in producing adult skills.

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- We relax the strong independence assumptions for error terms in the measurement equations that are maintained in Cunha and Heckman (2008) and Carneiro et al. (2003).
- The assumption of linearity of the technology in inputs that is used by Cunha and Heckman (2008) and Todd and Wolpin (2003, 2005) is not required because we allow inputs to interact in producing outputs.
- We generalize the factor-analytic index function models used by Carneiro et al. (2003) to allow for more general functional forms for measurement equations.



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- We determine the latent variables that generate test scores by estimating how these latent variables predict adult outcomes.
- Our approach sets the scale of test scores and latent variables in an interpretable metric.
- Using this metric, analysts can meaningfully interpret changes in output and conduct interpretable value-added analyses.

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- We allow for imperfect proxies and establish that measurement error is substantial in the data analyzed in this paper.

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- Present our identification analysis.
- Discuss the data used to estimate the model, our estimation strategy, and the model estimates.

## A Model of Cognitive and Noncognitive Skill Formation

• We analyze a model with multiple periods of childhood,  $t \in \{1, 2, ..., T\}$ ,  $T \ge 2$ , followed by A periods of adult working life,  $t \in \{T + 1, T + 2, ..., T + A\}$ .

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- Adult outcomes are produced by cognitive skills,  $\theta_{C,T+1}$ , and noncognitive skills,  $\theta_{N,T+1}$  at the beginning of the adult years.
- Denote parental investments at age t in child skill k by  $I_{k,t}$ ,  $k \in \{C, N\}.$

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- $\theta_t = (\theta_{C,t}, \theta_{N,t})$  denotes the vector of skill stocks in period t.
- Let  $\eta_t = (\eta_{C,t}, \eta_{N,t})$  denote shocks and/or unobserved inputs that affect the accumulation of cognitive and noncognitive skills, respectively.

$$\theta_{k,t+1} = f_{k,s} \left( \theta_t, I_{k,t}, \theta_P, \eta_{k,t} \right), \tag{1}$$

for 
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- Stocks of cognitive skills can promote the formation of noncognitive skills and *vice versa* because  $\theta_t$  is an argument of (1).

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Introduction

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 Period t stocks of abilities and skills promote the acquisition of skills by making investment more productive. • Direct complementarity between the stock of skill l and the productivity of investment  $l_{k,t}$  in producing skill k in period t arises if

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- Period t stocks of abilities and skills promote the acquisition of skills by making investment more productive.
- Students with greater early cognitive and noncognitive abilities are more efficient in later learning of both cognitive and noncognitive skills.
- The evidence from the early intervention literature suggests that the enriched early environments of the Abecedarian, Perry and Chicago Child-Parent Center (CPC) programs promoted greater efficiency in learning in high schools and reduced problem behaviors.

• Adult outcome j,  $Q_j$ , is produced by a combination of different skills at the beginning of period T + 1:

$$Q_j = g_j(\theta_{C,T+1}, \theta_{N,T+1}), \quad j \in \{1, \dots, J\}.$$
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 These outcome equations capture the twin concepts that both cognitive and noncognitive skills matter for performance in most tasks in life and have different effects in different tasks in the labor market and in other areas of social performance. • Adult outcome j,  $Q_j$ , is produced by a combination of different skills at the beginning of period T+1:

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- These outcome equations capture the twin concepts that both cognitive and noncognitive skills matter for performance in most tasks in life and have different effects in different tasks in the labor market and in other areas of social performance.
- Outcomes include test scores, schooling, wages, occupational attainment, hours worked, criminal activity, and teenage pregnancy.

• In this paper, we identify and estimate a *CES* version of technology (1) where we assume that  $\theta_{C,t}$ ,  $\theta_{N,t}$ ,  $I_{C,t}$ ,  $I_{N,t}$ ,  $\theta_{C,P}$ ,  $\theta_{N,P}$  are scalars.

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- Outputs of skills at stage s are governed by

$$\theta_{C,t+1} = \left[ \gamma_{s,C,1} \theta_{C,t}^{\phi_{s,C}} + \gamma_{s,C,2} \theta_{N,t}^{\phi_{s,C}} + \gamma_{s,C,3} I_{C,t}^{\phi_{s,C}} + \gamma_{s,C,4} \theta_{C,P}^{\phi_{s,C}} + \gamma_{s,C,5} \theta_{N,P}^{\phi_{s,C}} \right]^{\frac{1}{\phi_{s,C}}}$$
and
(3)

$$\theta_{N,t+1} = \left[ \gamma_{s,N,1} \theta_{C,t}^{\phi_{s,N}} + \gamma_{s,N,2} \theta_{N,t}^{\phi_{s,N}} + \gamma_{s,N,3} I_{N,t}^{\phi_{s,N}} + \gamma_{s,N,4} \theta_{C,P}^{\phi_{s,N}} + \gamma_{s,N,5} \theta_{N,P}^{\phi_{s,N}} \right]^{\frac{1}{\phi_{s,N}}}$$

where 
$$\gamma_{s,k,l} \in [0,1]$$
,  $\sum_{l} \gamma_{s,k,l} = 1$  for  $k \in \{C, N\}$ ,  $l \in \{1, ..., 5\}$ ,  $t \in \{1, ..., T\}$  and  $s \in \{1, ..., S\}$ .



•  $\frac{1}{1-\phi_{s,k}}$  is the elasticity of substitution in the inputs producing  $\theta_{k,t+1}$ , where  $\phi_{s,k} \in (-\infty,1]$  for  $k \in \{C,N\}$ .

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- It is a measure of how easy it is to compensate for low levels of stocks  $\theta_{C,t}$  and  $\theta_{N,t}$  inherited from the previous period with current levels of investment  $I_{C,t}$  and  $I_{N,t}$ .

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- For the moment, we ignore the shocks  $\eta_{k,t}$  in (1), although they play an important role in our empirical analysis.

$$Q_{j} = \left\{ \rho_{j} \left( \theta_{C,T+1} \right)^{\phi_{Q,j}} + (1 - \rho_{j}) \left( \theta_{N,T+1} \right)^{\phi_{Q,j}} \right\}^{\frac{1}{\phi_{Q,j}}}, \quad (5)$$

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- $\frac{1}{1-\phi_{Q,j}}$  is the elasticity of substitution across different skills in the production of outcome j.
- The ability of noncognitive skills to compensate for cognitive deficits in producing adult outcomes is governed by  $\phi_{Q,j}$ .
- The importance of cognition in producing output in task j is governed by the share parameter  $\rho_j$ .

• To gain some insight into this model, consider a special case investigated in Cunha and Heckman (2007) where childhood lasts two periods (T=2), there is one adult outcome ("human capital") so J=1, and the elasticities of substitution are the same across technologies (3) and (4) and in the outcome (5), so  $\phi_{s,C}=\phi_{s,N}=\phi_{Q}=\phi$  for all  $s\in\{1,\ldots,S\}$ .

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- Assume that there is one investment good in each period that increases both cognitive and noncognitive skills, though not necessarily by the same amount,  $(I_{k,t} \equiv I_t, k \in \{C, N\})$ .

 In this case, the adult outcome is a function of investments, initial endowments, and parental characteristics and can be written as

$$Q = \left[\tau_1 I_1^{\phi} + \tau_2 I_2^{\phi} + \tau_3 \theta_{C,1}^{\phi} + \tau_4 \theta_{N,1}^{\phi} + \tau_5 \theta_{C,P}^{\phi} + \tau_6 \theta_{N,P}^{\phi}\right]^{\frac{1}{\phi}}, (6)$$

where  $\tau_i$  for  $i=1,\ldots,6$  depend on the parameters of equations (3)–(5).

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where  $\tau_i$  for i = 1, ..., 6 depend on the parameters of equations (3)–(5).

 Cunha and Heckman (2007) analyze the optimal timing of investment using a special version of the technology embodied in (6). • Let  $R(Q) = \sum_{t=2}^{A+2} \left(\frac{1}{1+r}\right)^t wQ$  denote the net present value of the child's future income computed with respect to the date of birth.

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- Parents have resources M that they use to invest in period "1",  $I_1$ , and period "2",  $I_2$ .
- The objective of the parent is to maximize the net present value of the child's future income given parental resource constraints.
- Assuming an interior solution, that the price of investment in period "1" is one, the relative price of investment in period "2" is  $\frac{1}{1+r}$ , the optimal ratio of period "1" investment to period "2" investment is

$$\log\left(\frac{I_1}{I_2}\right) = \left(\frac{1}{1-\phi}\right) \left[\log\left(\frac{\tau_1}{\tau_2}\right) - \log\left(1+r\right)\right]. \tag{7}$$

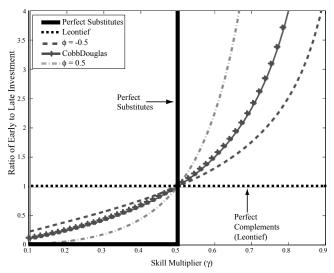


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- Ceteris paribus, the higher  $\tau_1$  relative to  $\tau_2$ , the higher first period investment should be relative to second period investment.

- Figure 1 plots the ratio of early to late investment as a function of  $\tau_1/\tau_2$  for different values of  $\phi$ .
- Ceteris paribus, the higher  $\tau_1$  relative to  $\tau_2$ , the higher first period investment should be relative to second period investment.
- The parameters  $\tau_1$  and  $\tau_2$  are determined in part by the productivity of investments in producing skills, which are generated by the technology parameters  $\gamma_{s,k,3}$ , for  $s \in \{1,2\}$  and  $k \in \{C,N\}$ .

Ratio of early to late investment in human capital as a function of the ratio of first period to second period investment productivity for different values of the complementarity parameter



Note: Assumes r = 0.

Source: Cunha and Heckman (2007).



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- Ceteris paribus , if  $\frac{\tau_1}{\tau_2} > (1+r)$ , the higher the CES complementarity, (i.e., the lower  $\phi$ ), the greater is the ratio of optimal early to late investment.
- The greater *r*, the smaller should be the optimal ratio of early to late investment.
- In the limit, if investments complement each other strongly, optimality implies that they should be equal in both periods.



• To see how these parameters affect the optimal ratio of early to late investment, suppose that early investment only produces cognitive skill, so that  $\gamma_{1,N,3}=0$ , and late investment only produces noncognitive skill, so that  $\gamma_{2,C,3}=0$ .

- To see how these parameters affect the optimal ratio of early to late investment, suppose that early investment only produces cognitive skill, so that  $\gamma_{1,N,3}=0$ , and late investment only produces noncognitive skill, so that  $\gamma_{2,C,3}=0$ .
- In this case, the ratio  $\left(\frac{\tau_1}{\tau_2}\right)$  can be expressed in terms of the technology and outcome function parameters:

$$\left(\frac{\tau_{1}}{\tau_{2}}\right) = \frac{\left(\rho\gamma_{2,C,1} + \left(1 - \rho\right)\gamma_{2,N,1}\right)}{\left(1 - \rho\right)} \frac{\gamma_{1,C,3}}{\gamma_{2,N,3}}.$$

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• For a given value of  $\rho$  (the weight placed on cognition in determining final outcomes), the ratio of early to late investment is higher the greater the ratio  $\frac{\gamma_{1,C,3}}{\gamma_{2,N,3}}$ .

• To investigate the role  $\rho$  plays in determining the optimal ratio of investments, assume that  $\gamma_{2,C,1} \geq \gamma_{2,N,1}$ , so that the stock of cognitive skill,  $\theta_{C,1}$ , is at least as effective in producing next period cognitive skill,  $\theta_{C,2}$ , as it is in producing next period noncognitive skill,  $\theta_{N,2}$ .

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- Under this assumption, the higher  $\rho$ , that is, the more important cognitive skills are in producing Q, the higher the equilibrium ratio  $I_1/I_2$ .
- If, on the other hand, Q is more intensive in noncognitive skills, then  $I_1/I_2$  is smaller.

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- However, it oversimplifies the analysis of skill formation.
- It is implausible that the elasticity of substitution between skills in producing adult outcomes  $(\frac{1}{1-\phi_Q})$  is the same as the elasticity of substitution between inputs in producing skills, and that a common elasticity of substitution governs the productivity of inputs in producing both cognitive and noncognitive skills.

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- We allow the elasticities of substitution governing the technologies for producing cognitive and noncognitive skills to differ at different stages of the life cycle and for both to be different from the elasticities of substitution for cognitive and noncognitive skills in producing adult outcomes.
- We test and reject the assumption that  $\phi_{s,C} = \phi_{s,N}$  for  $s \in \{1, \dots, S\}$ .

• Identifying and estimating technology (1) is challenging.



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- Inputs may be endogenous and the unobservables in the input equations may be correlated with unobservables in the technology equations.

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  - ① Determine how stocks of cognitive and noncognitive skills at date t affect the stocks of skills at date t+1, identifying both self productivity (the effects of  $\theta_{N,t}$  on  $\theta_{N,t+1}$ , and  $\theta_{C,t}$  on  $\theta_{C,t+1}$ ) and cross productivity (the effects of  $\theta_{C,t}$  on  $\theta_{N,t+1}$  and the effects of  $\theta_{N,t}$  on  $\theta_{C,t+1}$ ) at each stage of the life cycle.

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  - ② Develop a non-linear dynamic factor model where  $(\theta_t, I_t, \theta_P)$  is proxied by vectors of measurements which include test scores and input measures as well as outcome measures. In our analysis, test scores and personality evaluations are indicators of latent skills. Parental inputs are indicators of latent investment. We account for measurement error in these proxies.

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  - ② Develop a non-linear dynamic factor model where  $(\theta_t, I_t, \theta_P)$  is proxied by vectors of measurements which include test scores and input measures as well as outcome measures. In our analysis, test scores and personality evaluations are indicators of latent skills. Parental inputs are indicators of latent investment. We account for measurement error in these proxies.
  - Stimate the elasticities of substitution for the technologies governing the production of cognitive and noncognitive skills.

Anchor the scale of test scores using adult outcome measures instead of relying on test scores as measures of output. This allows us to avoid relying on arbitrary test scores as measurements of output. Any monotonic function of a test score is still a valid test score.

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- Account for the endogeneity of parental investments when parents make child investment decisions in response to the characteristics of the child that may change over time as the child develops and as new information about the child is revealed.

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- We start with a model where measurements are linear and separable in the latent variables, as in Cunha and Heckman (2008).
- We establish identification of the joint distribution of the latent variables without imposing conventional independence assumptions about measurement errors.
- With the joint distribution of latent variables in hand, we nonparametrically identify technology (1) given alternative assumptions about  $\eta_{k,t}$ .

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- We anchor the latent variables in adult outcomes to make their scales interpretable.
- Finally, we account for endogeneity of inputs in the technology equations and model investment behavior.

#### Identifying the Distribution of the Latent Variables

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- We have measurements on test scores and parental and teacher assessments of skills (a = 1), on investment (a = 2) and on parental endowments (a = 3).
- Each measurement has a cognitive and noncognitive component so  $k \in \{C, N\}$ .



• We initially assume that measurements are additively separable functions of the latent factors  $\theta_{k,t}$  and  $I_{k,t}$ :

$$Z_{1,k,t,j} = \mu_{1,k,t,j} + \alpha_{1,k,t,j} \theta_{k,t} + \varepsilon_{1,k,t,j}$$
(8)

$$Z_{2,k,t,j} = \mu_{2,k,t,j} + \alpha_{2,k,t,j} I_{k,t} + \varepsilon_{2,k,t,j}, \tag{9}$$

where  $E(\varepsilon_{a,k,t,j}) = 0$ ,  $j \in \{1, ..., M_{a,k,t}\}$ ,  $t \in \{1, ..., T\}$ ,  $k \in \{C, N\}$ ,  $a \in \{1, 2\}$  and where  $\varepsilon_{a,k,t,j}$  are uncorrelated across the j.

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• Assuming that parental endowments are measured only once in period t=1, we write

$$Z_{3,k,1,j} = \mu_{3,k,1,j} + \alpha_{3,k,1,j}\theta_{k,P} + \varepsilon_{3,k,1,j},$$

$$E(\varepsilon_{3,k,1,j}) = 0, j \in \{1, \dots, M_{3,k,1}\}, \text{ and } k \in \{C, N\}.$$
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- Separability makes the identification analysis transparent.
- We consider a more general nonseparable model below.
- Given measurements  $Z_{a,k,t,j}$ , we can identify the mean functions  $\mu_{a,k,t,j}$ ,  $a \in \{1,2,3\}$ ,  $t \in \{1,\ldots,T\}$ ,  $k \in \{C,N\}$ , which may depend on the X.

Identification of the Factor Loadings and of the Joint Distributions of the Latent Variables

• We first establish identification of the factor loadings under the assumption that the  $\varepsilon_{a,k,t,j}$  are uncorrelated across t and that the analyst has at least two measures of each type of child skills and investments in each period t, where T > 2.

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- Without loss of generality, we focus on  $\alpha_{1,C,t,j}$  and note that similar expressions can be derived for the loadings of the other latent factors.

• Since  $Z_{1,C,t,1}$  and  $Z_{1,C,t+1,1}$  are observed, we can compute  $Cov\left(Z_{1,C,t,1},Z_{1,C,t+1,1}\right)$  from the data.

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- Because of the normalization  $\alpha_{1,C,t,1} = 1$  for all t, we obtain:

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• In addition, we can compute the covariance of the second measurement on cognitive skills at period t with the first measurement on cognitive skills at period t+1:

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• If  $Cov(\theta_{C,t}, \theta_{C,t+1}) \neq 0$ , one can identify the loading  $\alpha_{1,C,t,2}$  from the following ratio of covariances:

$$\frac{Cov(Z_{1,C,t,2},Z_{1,C,t+1,1})}{Cov(Z_{1,C,t,1},Z_{1,C,t+1,1})} = \alpha_{1,C,t,2}.$$



• If there are more than two measures of cognitive skill in each period t, we can identify  $\alpha_{1,C,t,j}$  for  $j \in \{2,3,\ldots,M_{1,C,t}\}$ ,  $t \in \{1,\ldots,T\}$  up to the normalization  $\alpha_{1,C,t,1}=1$ .

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- Replacing  $Z_{1,C,t+1,1}$  by  $Z_{a',k',t',3}$  for some (a',k',t') which may or may not be equal to (1,C,t), we may proceed in the same fashion.

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- Note that the same third measurement  $Z_{a',k',t',3}$  can be reused for all a, t and k implying that in the presence of serial correlation, the total number of measurements needed for identification of the factor loadings is 2L+1 if there are L factors.



$$\frac{Z_{1,C,t,j}}{\alpha_{1,C,t,j}} = \frac{\mu_{1,C,t,j}}{\alpha_{1,C,t,j}} + \theta_{C,t} + \frac{\varepsilon_{1,C,t,j}}{\alpha_{1,C,t,j}}, j \in \{1, 2, \dots, M_{1,C,t}\}.$$
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- Collecting results for all  $t=1,\ldots,T$ , we can identify the joint distribution of  $\{\theta_{C,t}\}_{t=1}^T$ .
- Proceeding in a similar fashion for all types of measurements,  $a \in \{1, 2, 3\}$ , on abilities  $k \in \{C, N\}$ , using the analysis in Schennach (2004a,b), we can identify the joint distribution of all the latent variables.



$$\theta = \left( \left\{ \theta_{C,t} \right\}_{t=1}^{T}, \left\{ \theta_{N,t} \right\}_{t=1}^{T}, \left\{ I_{C,t} \right\}_{t=1}^{T}, \left\{ I_{N,t} \right\}_{t=1}^{T}, \theta_{C,P}, \theta_{N,P} \right).$$

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• Thus, we can identify the joint distribution of  $\theta$ ,  $p(\theta)$ .

 Although the availability of numerous indicators for each latent factor is helpful in improving the efficiency of the estimation procedure, the identification of the model can be secured (after the factor loadings are determined) if only two measurements of each latent factor are available.

- Although the availability of numerous indicators for each latent factor is helpful in improving the efficiency of the estimation procedure, the identification of the model can be secured (after the factor loadings are determined) if only two measurements of each latent factor are available.
- Since in our empirical analysis we have at least two different measurements for each latent factor, we can define, without loss of generality, the following two vectors

$$W_{i} = \left( \left\{ \frac{Z_{1,C,t,i}}{\alpha_{1,C,t,i}} \right\}_{t=1}^{T}, \left\{ \frac{Z_{1,N,t,i}}{\alpha_{1,N,t,i}} \right\}_{t=1}^{T}, \left\{ \frac{Z_{2,C,t,i}}{\alpha_{2,C,t,i}} \right\}_{t=1}^{T}, \left\{ \frac{Z_{2,N,t,i}}{\alpha_{2,N,t,i}} \right\}_{t=1}^{T},$$

$$\frac{Z_{3,C,1,i}}{\alpha_{3,C,1,i}}, \frac{Z_{3,N,1,i}}{\alpha_{3,N,1,i}} \right)'$$

$$i \in \{1,2\}.$$

• These vectors consist of the first and the second measurements for each factor, respectively.

- These vectors consist of the first and the second measurements for each factor, respectively.
- The corresponding measurement errors are

$$\omega_{i} = \left( \left\{ \frac{\varepsilon_{1,C,t,i}}{\alpha_{1,C,t,i}} \right\}_{t=1}^{T}, \left\{ \frac{\varepsilon_{1,N,t,i}}{\alpha_{1,N,t,i}} \right\}_{t=1}^{T}, \left\{ \frac{\varepsilon_{2,C,t,i}}{\alpha_{2,C,t,i}} \right\}_{t=1}^{T}, \left\{ \frac{\varepsilon_{2,N,t,i}}{\alpha_{2,N,t,i}} \right\}_{t=1}^{T}, \left\{ \frac{\varepsilon_{2,N,t,i}}{\alpha_{2,N,t,i}} \right\}_{t=1}^{T}, i \in \{1,2\}.$$

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- Identification of the distribution of  $\theta$  is obtained from the following theorem.
- Let L denote the total number of latent factors, which in our case is 4T + 2.

## **Theorem**

Let  $W_1$ ,  $W_2$ ,  $\theta$ ,  $\omega_1$ ,  $\omega_2$  be random vectors taking values in  $\mathbb{R}^L$  and related through

$$W_1 = \theta + \omega_1 W_2 = \theta + \omega_2.$$

If (i)  $E[\omega_1|\theta,\omega_2]=0$  and (ii)  $\omega_2$  is independent from  $\theta$ , then the density of  $\theta$  can be expressed in terms of observable quantities as:

$$p_{\theta}\left(\theta\right) = \left(2\pi\right)^{-L} \int e^{-i\chi \cdot \theta} \exp\left(\int_{0}^{\chi} \frac{E\left[iW_{1}e^{i\zeta \cdot W_{2}}\right]}{E\left[e^{i\zeta \cdot W_{2}}\right]} \cdot d\zeta\right) d\chi,$$

where in this expression  $i=\sqrt{-1}$ , provided that all the requisite expectations exist and  $E\left[e^{i\zeta\cdot W_2}\right]$  is nonvanishing. Note that the innermost integral is the integral of a vector-valued field along a continuous path joining the origin and the point  $\chi\in\mathbb{R}^L$ , while the outermost integral is over the whole  $\mathbb{R}^L$  space.

## **Theorem**

If  $\theta$  does not admit a density with respect to the Lebesgue measure,  $p_{\theta}(\theta)$  can be interpreted within the context of the theory of distributions. If some elements of  $\theta$  are perfectly measured, one may simply set the corresponding elements of  $W_1$  and  $W_2$  to be equal. In this way, the joint distribution of mismeasured and perfectly measured variables is identified.

• **Proof.** See Web Appendix, Part 3.1.

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- For example, our analysis allows analysts to accommodate heteroscedasticity in the distribution of  $\omega_1$  that may depend on  $\omega_2$  and  $\theta$ .
- It also allows for potential correlation of components within the vectors  $\omega_1$  and  $\omega_2$ , thus permitting serial correlation within a given set of measurements.

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- In order to extract the noise from the signal, the disturbances have to satisfy some form of orthogonality with respect to the signal and with respect to each other.
- These conditions are various uncorrelatedness assumptions, conditional mean assumptions, or conditional independence assumptions.
- They are used in various combinations in Theorem 1, in Theorem 2 below and in other results in this paper.



## The Identification of a General Measurement Error Model

 We extend the previous analysis for linear factor models to consider a measurement model of the general form

$$Z_j = a_j(\theta, \varepsilon_j) \text{ for } j \in \{1, \dots, M\},$$
 (14)

where  $M \geq 3$  and where the indicator  $Z_j$  is observed while the latent factor  $\theta$  and the disturbance  $\varepsilon_j$  are not.

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where  $M \geq 3$  and where the indicator  $Z_j$  is observed while the latent factor  $\theta$  and the disturbance  $\varepsilon_j$  are not.

• The variables  $Z_j$ ,  $\theta$ , and  $\varepsilon_j$  are assumed to be vectors of the same dimension.

 In our application, the vector of observed indicators and corresponding disturbances is

$$\begin{split} Z_{j} &= \left( \left\{ Z_{1,C,t,j} \right\}_{t=1}^{T}, \left\{ Z_{1,N,t,j} \right\}_{t=1}^{T}, \left\{ Z_{2,C,t,j} \right\}_{t=1}^{T}, \left\{ Z_{2,N,t,j} \right\}_{t=1}^{T}, Z_{3,C,1,j}, Z_{3,N,1,j} \right)' \\ \varepsilon_{j} &= \left( \left\{ \varepsilon_{1,C,t,j} \right\}_{t=1}^{T}, \left\{ \varepsilon_{1,N,t,j} \right\}_{t=1}^{T}, \left\{ \varepsilon_{2,C,t,j} \right\}_{t=1}^{T}, \left\{ \varepsilon_{2,N,t,j} \right\}_{t=1}^{T}, \varepsilon_{3,C,1,j}, \varepsilon_{3,C,N,1,j} \right)' \end{split}$$

while the vector of unobserved latent factors is:

$$\theta = \left( \left\{ \theta_{C,t} \right\}_{t=1}^{T}, \left\{ \theta_{N,t} \right\}_{t=1}^{T}, \left\{ I_{C,t} \right\}_{t=1}^{T}, \left\{ I_{N,t} \right\}_{t=1}^{T}, \theta_{C,P}, \theta_{N,P} \right)'.$$

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- The functions  $a_j(\cdot, \cdot)$  for  $j \in \{1, ..., M\}$  in Equations (14) are unknown.
- It is necessary to normalize one of them (e.g.,  $a_1(\cdot, \cdot)$ ) in some way to achieve identification, as established in the following theorem.

## **Theorem**

The distribution of  $\theta$  in Equations (14) is identified under the following conditions:

- **1** The joint density of  $\theta$ ,  $Z_1$ ,  $Z_2$ ,  $Z_3$  is bounded and so are all their marginal and conditional densities.
- ②  $Z_1$ ,  $Z_2$ ,  $Z_3$  are mutually independent conditional on  $\theta$ .
- **3**  $p_{Z_1|Z_2}(Z_1 \mid Z_2)$  and  $p_{\theta|Z_1}(\theta \mid Z_1)$  form a bounded, complete family of distributions indexed by  $Z_2$  and  $Z_1$ , respectively.
- Whenever  $\theta \neq \tilde{\theta}$ ,  $p_{Z_3|\theta}\left(Z_3 \mid \theta\right)$  and  $p_{Z_3|\theta}\left(Z_3 \mid \tilde{\theta}\right)$  differ over a set of strictly positive probability.
- **5** There exists a known functional  $\Psi$ , mapping a density to a vector, that has the property that  $\Psi \left[ p_{Z_1 \mid \theta} \left( \cdot \mid \theta \right) \right] = \theta$ .



**Proof.** See Web Appendix, Part 3.2.

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- In contrast to the standard matrix diagonalization used in linear factor analyses, we do not work with random vectors.
- Instead, we work with their densities.
- This approach offers the advantage that the problem remains linear even when the random vectors are related nonlinearly.

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- Assumption 3 requires  $\theta$ ,  $Z_1$ ,  $Z_2$  to be vectors of the same dimensions, while Assumption 4 can be satisfied even if  $Z_3$  is a scalar.
- The minimum number of measurements needed for identification is therefore 2L+1, which is exactly the same number of measurements as in the linear, classical measurement error case.

 Versions of Assumption 3 appear in the nonparametric instrumental variable literature (e.g., Newey and Powell, 2003; Darolles et al., 2002).

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- Intuitively, the requirement that  $p_{Z_1|Z_2}(Z_1|Z_2)$  forms a bounded complete family requires that the density of  $Z_1$  vary sufficiently as  $Z_2$  varies (and similarly for  $p_{\theta|Z_1}(\theta|Z_1)$ ).

• Assumption 4 is automatically satisfied, for instance, if  $\theta$  is univariate and  $a_3(\theta, \varepsilon_3)$  is strictly increasing in  $\theta$ .

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- However, it holds much more generally.
- Since  $a_3(\theta, \varepsilon_3)$  is nonseparable, the distribution of  $Z_3$  conditional on  $\theta$  can change with  $\theta$ , thus making it possible for Assumption 4 to be satisfied even if  $a_3(\theta, \varepsilon_3)$  is not strictly increasing in  $\theta$ .

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- One way to satisfy this assumption is to normalize  $a_1(\theta, \varepsilon_1)$  to be equal to  $\theta + \varepsilon_1$ , where  $\varepsilon_1$  has zero mean, median or mode.
- The zero mode assumption is particularly plausible for surveys where respondents face many possible wrong answers but only one correct answer.

 Moving the mode of the answers away from zero would therefore require a majority of respondents to misreport in exactly the same way— an unlikely scenario.

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- Many other nonseparable functions can also satisfy this assumption.
- With the distribution of  $p_{\theta}(\theta)$  in hand, we can identify the technology using the analysis presented below.

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- In fact, it is always possible to alter the distribution of  $\varepsilon_j$  and the dependence of the function  $a_j(\cdot,\cdot)$  on its second argument in ways that cancel each other out, as noted in the literature on nonseparable models.

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- In fact, it is always possible to alter the distribution of  $\varepsilon_j$  and the dependence of the function  $a_j(\cdot,\cdot)$  on its second argument in ways that cancel each other out, as noted in the literature on nonseparable models.
- However, lack of identifiability of these features of the model does not prevent identification of the distribution of  $\theta$ .

• Nevertheless, various normalizations ensuring that the functions  $a_j(\theta, \varepsilon_j)$  are fully identified are available.

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- We invoke these assumptions when we identify the policy function for investments below.



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- Their different assumptions represent different trade-offs best suited for different applications.
- While Theorem 1 would suffice for the empirical analysis of this paper, the general result established in Theorem 3 will likely be quite useful as larger sample sizes become available.

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- Our approach for identifying the distribution of  $\theta$  from general nonseparable measurement equations does not require these strong assumptions.
- Note that it also allows the  $\theta$  to determine all measurements and for the  $\theta$  to be freely correlated.

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- Below, we analyze a more general case that allows for serial dependence.
- Once the density of  $\theta$  is known, one can identify nonseparable technology function (1) for  $t \in \{1, ..., T\}$ ;  $k \in \{C, N\}$ ; and  $s \in \{1, ..., S\}$ .
- Even if  $(\theta_t, I_t, \theta_P)$  were perfectly observed, one could not separately identify the distribution of  $\eta_{k,t}$  and the function  $f_{k,s}$  because, without further normalizations, a change in the density of  $\eta_{k,t}$  can be undone by a change in the function  $f_{k,s}$ .



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- Another way to avoid this ambiguity is to normalize  $\eta_{k,t}$  to have a uniform density on [0,1].
- Any of the normalizations suggested by Matzkin (2003, 2007) could be used.
- Assuming  $\eta_{k,t}$  is uniform [0,1], we establish that  $f_{k,s}$  is nonparametrically identified, by noting that, from the knowledge of  $p_{\theta}$  we can calculate, for any  $\bar{\theta} \in \mathbb{R}$ ,

$$\Pr\left[\theta_{k,t+1} \leq \bar{\theta} | \theta_t, I_{k,t}, \theta_P\right] \equiv G\left(\bar{\theta} | \theta_t, I_{k,t}, \theta_P\right).$$



• We identify technology (1) using the relationship

$$f_{k,s}\left(\theta_{t},I_{k,t},\theta_{P}\right)=G^{-1}\left(\eta_{k,t}|\theta_{t},I_{k,t},\theta_{P}\right)$$

where  $G^{-1}(\eta_{k,t} \mid \theta_t, I_{k,t}, \theta_P)$  denotes the inverse of  $G(\bar{\theta} \mid \theta_t, I_{k,t}, \theta_P)$  with respect to its first argument, i.e., the value  $\bar{\theta}$  such that  $\eta_{k,t} = G(\bar{\theta} \mid \theta_t, I_{k,t}, \theta_P)$ .

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• By construction, this operation produces a function  $f_{k,s}$  that generates outcomes  $\theta_{k,t+1}$  with the appropriate distribution, because a random variable is mapped into a uniformly distributed variable under the mapping defined by its own cdf.

• The more traditional separable technology with zero mean disturbance,  $\theta_{k,t+1} = f_{k,s}\left(\theta_t, I_{k,t}, \theta_P\right) + \eta_{k,t}$ , is covered by our analysis if we define

$$f_{k,s}\left(\theta_{t},I_{k,t},\theta_{P}\right)\equiv E\left[\theta_{k,t+1}\mid\theta_{t},I_{k,t},\theta_{P}\right]$$
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where the expectation is taken under the density  $p_{\theta_{k,t+1}|\theta_t,I_{k,t},\theta_P}$ , which can be calculated from  $p_{\theta}$ .

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$$\begin{aligned} & p_{\theta_{k,t+1}|\theta_t,I_{k,t},\theta_P} \left( \eta_{k,t} \mid \theta_t, I_{k,t}, \theta_P \right) \\ & = p_{\theta_{k,t+1}|\theta_t,I_{k,t},\theta_P} \left( \eta_{k,t} + E \left[ \theta_{k,t+1} \mid \theta_t, I_{k,t}, \theta_P \right] \mid \theta_t, I_{k,t}, \theta_P \right), \end{aligned}$$

since  $p_{\theta_{k,t+1}|\theta_t,I_{k,t},\theta_P}$  is known once  $p_{\theta}$  is known.

References

Introduction

• The more traditional separable technology with zero mean disturbance,  $\theta_{k,t+1} = f_{k,s} \left( \theta_t, I_{k,t}, \theta_P \right) + \eta_{k,t}$ , is covered by our analysis if we define

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since  $p_{\theta_{k,t+1}|\theta_t,I_{k,t},\theta_P}$  is known once  $p_{\theta}$  is known.

• We now show how to anchor the scales of  $\theta_{C,t+1}$  and  $\theta_{N,t+1}$  using measures of adult outcomes.

Anchoring Skills in an Interpretable Metric

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- However, test scores are arbitrarily scaled.
- To gain a better understanding of the relative importance of cognitive and noncognitive skills and their interactions and the relative importance of investments at different stages of the life cycle, it is desirable to anchor skills in a common scale.
- In what follows, we continue to keep the conditioning on the regressors implicit.

• We model the effect of period T+1 cognitive and noncognitive skills on adult outcomes  $Z_{4,j}$ , for  $j \in \{1, ..., J\}$ .

- We model the effect of period T+1 cognitive and noncognitive skills on adult outcomes  $Z_{4,j}$ , for  $j \in \{1, \ldots, J\}$ .
- functions of cognitive and noncognitive skills at the end of childhood, i.e., in period  $\mathcal{T}$ :

• Suppose that there are  $J_1$  observed outcomes that are linear

$$Z_{4,j} = \mu_{4,j} + \alpha_{4,C,j}\theta_{C,T+1} + \alpha_{4,N,j}\theta_{N,T+1} + \varepsilon_{4,j}, \text{ for } j \in \{1,\ldots,J_1\}.$$

- We model the effect of period T+1 cognitive and noncognitive skills on adult outcomes  $Z_{4,j}$ , for  $j \in \{1, \ldots, J\}$ .
- Suppose that there are  $J_1$  observed outcomes that are linear functions of cognitive and noncognitive skills at the end of childhood, i.e., in period T:

$$Z_{4,j} = \mu_{4,j} + \alpha_{4,C,j}\theta_{C,T+1} + \alpha_{4,N,j}\theta_{N,T+1} + \varepsilon_{4,j}, \text{ for } j \in \{1,\ldots,J_1\}.$$

 When adult outcomes are linear and separable functions of skills, we can define the anchoring functions to be:

$$g_{C,j}(\theta_{C,T+1}) = \mu_{4,j} + \alpha_{4,C,j}\theta_{C,T+1}$$

$$g_{N,j}(\theta_{N,T+1}) = \mu_{4,j} + \alpha_{4,N,j}\theta_{N,T+1}.$$
(15)



• We can also anchor using nonlinear functions.

- We can also anchor using nonlinear functions.
- One example would be an outcome produced by a latent variable  $Z_{4,j}^*$ , for  $j \in \{J_1 + 1, \dots, J\}$ :

$$Z_{4,j}^* = \tilde{g}_j \left( \theta_{C,T+1}, \theta_{N,T+1} \right) - \varepsilon_{4,j}.$$

 One example would be an outcome produced by a latent variable  $Z_{4,i}^*$ , for  $j \in \{J_1 + 1, ..., J\}$ :

$$Z_{4,j}^* = \tilde{g}_j \left( \theta_{C,T+1}, \theta_{N,T+1} \right) - \varepsilon_{4,j}.$$

• Note that we do not observe  $Z_{4,i}^*$ , but we observe the variable  $Z_{4,i}$  which is defined as:

$$Z_{4,j} = \begin{cases} 1, & \text{if } \tilde{g}_j \left( \theta_{C,T+1}, \theta_{N,T+1} \right) - \varepsilon_{4,j} \ge 0 \\ 0, & \text{otherwise.} \end{cases}$$

#### In this notation

$$\Pr(Z_{4,j} = 1 | \theta_{C,T+1}, \theta_{N,T+1}) = \Pr[\varepsilon_{4,j} \leq \tilde{g}_{j} (\theta_{C,T+1}, \theta_{N,T+1}) | \theta_{C,T+1}, \theta_{N,T+1}] = F_{\varepsilon_{4,j}} [\tilde{g}_{j} (\theta_{C,T+1}, \theta_{N,T+1}) | \theta_{C,T+1}, \theta_{N,T+1}] = g_{j} (\theta_{C,T+1}, \theta_{N,T+1}).$$

In this notation

$$\begin{aligned} & \Pr\left( \left. Z_{4,j} = 1 \right| \theta_{C,T+1}, \theta_{N,T+1} \right) \\ & = \Pr\left[ \left. \varepsilon_{4,j} \leq \tilde{g}_{j} \left( \theta_{C,T+1}, \theta_{N,T+1} \right) \right| \theta_{C,T+1}, \theta_{N,T+1} \right] \\ & = F_{\varepsilon_{4,j}} \left[ \tilde{g}_{j} \left( \theta_{C,T+1}, \theta_{N,T+1} \right) \right| \theta_{C,T+1}, \theta_{N,T+1} \right] \\ & = g_{j} \left( \theta_{C,T+1}, \theta_{N,T+1} \right). \end{aligned}$$

 Adult outcomes such as high school graduation, criminal activity, drug use, and teenage pregnancy may be represented in this fashion. • To establish identification of  $g_j(\theta_{C,T+1},\theta_{N,T+1})$  for  $j \in \{J_1+1,\ldots,J\}$ , we include the dummy  $Z_{4,j}$  in the vector  $\theta$ .

- To establish identification of  $g_i(\theta_{C,T+1},\theta_{N,T+1})$  for  $j \in \{J_1 + 1, \dots, J\}$ , we include the dummy  $Z_{4,j}$  in the vector  $\theta$ .
- Assuming that the dummy  $Z_{4,i}$  is measured without error, the corresponding element of the two repeated measurement vectors  $W_1$  and  $W_2$  are identical and equal to  $Z_{4,i}$ .

- To establish identification of  $g_j(\theta_{C,T+1},\theta_{N,T+1})$  for  $j \in \{J_1+1,\ldots,J\}$ , we include the dummy  $Z_{4,j}$  in the vector  $\theta$ .
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- Theorem 1 implies that the joint density of  $Z_{4,j}$ ,  $\theta_{C,t}$  and  $\theta_{N,t}$  is identified.

- To establish identification of  $g_j(\theta_{C,T+1},\theta_{N,T+1})$  for  $j \in \{J_1+1,\ldots,J\}$ , we include the dummy  $Z_{4,j}$  in the vector  $\theta$ .
- Assuming that the dummy  $Z_{4,j}$  is measured without error, the corresponding element of the two repeated measurement vectors  $W_1$  and  $W_2$  are identical and equal to  $Z_{4,j}$ .
- Theorem 1 implies that the joint density of  $Z_{4,j}$ ,  $\theta_{C,t}$  and  $\theta_{N,t}$  is identified.
- Thus, it is possible to identify  $\Pr[Z_{4,j} = 1 \mid \theta_{C,T+1}, \theta_{N,T+1}].$

• We can extract two separate "anchors"  $g_{C,j}(\theta_{C,T+1})$  and  $g_{N,j}(\theta_{N,T+1})$  from the function  $g_j(\theta_{C,T+1},\theta_{N,T+1})$ , by integrating out the other variable, e.g.,

$$g_{C,j}(\theta_{C,T+1}) \equiv \int g_j(\theta_{C,T+1},\theta_{N,T+1}) p_{\theta_{N,T+1}}(\theta_{N,T+1}) d\theta_{N,T+1},$$
(16)

$$g_{N,j}(\theta_{N,T+1}) \equiv \int g_j(\theta_{C,T+1},\theta_{N,T+1}) p_{\theta_{C,T+1}}(\theta_{C,T+1}) d\theta_{C,T+1},$$

where the marginal densities,  $p_{\theta_{j,T}}(\theta_{N,T+1})$ ,  $j \in \{C, N\}$  are identified by applying the preceding analysis.

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where the marginal densities,  $p_{\theta_{j,T}}(\theta_{N,T+1})$ ,  $j \in \{C, N\}$  are identified by applying the preceding analysis.

• Both  $g_{C,j}(\theta_{C,T+1})$  and  $g_{N,j}(\theta_{N,T+1})$  are assumed to be strictly monotonic in their arguments.



ullet The "anchored" skills, denoted by  $ilde{ heta}_{j,k,t}$ , are defined as

$$\tilde{\theta}_{j,k,t} = g_{k,j}(\theta_{k,t}), k \in \{C, N\}, t \in \{1, \dots, T\}.$$

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,  $k \in \{C, N\}$ ,  $t \in \{1, \dots, T\}$ .

 The anchored skills inherit the subscript j because different anchors generally scale the same latent variables differently. • We combine the identification of the anchoring functions with the identification of the technology function  $f_{k,s}\left(\theta_{t},I_{k,t},\theta_{P},\eta_{k,t}\right)$  established previously to prove that the technology function expressed in terms of the anchored skills—denoted by  $\tilde{f}_{k,s,j}\left(\tilde{\theta}_{j,t},I_{k,t},\theta_{P},\eta_{k,t}\right)$ — is also identified.

To do so, redefine the technology function to be

$$\begin{split} &\tilde{f}_{k,s,j}\left(\tilde{\theta}_{j,C,t},\tilde{\theta}_{j,N,t},I_{k,t},\theta_{C,P},\theta_{N,P},\eta_{k,t}\right) \\ &\equiv g_{k,j}\left(f_{k,s}\left(g_{C,j}^{-1}\left(\tilde{\theta}_{j,C,t}\right),g_{N,j}^{-1}\left(\tilde{\theta}_{j,N,t}\right),I_{k,t},\theta_{C,P},\theta_{N,P},\eta_{k,t}\right)\right), \\ &k \in \{C,N\} \end{split}$$

where  $g_{k,j}^{-1}(\cdot)$  denotes the inverse of the function  $g_{k,j}(\cdot)$ .



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where  $g_{k,j}^{-1}(\cdot)$  denotes the inverse of the function  $g_{k,j}(\cdot)$ .

• Invertibility follows from the assumed monotonicity.



### • It is straightforward to show that

$$\begin{split} \tilde{f}_{k,s,j} \left( \tilde{\theta}_{j,C,t}, \tilde{\theta}_{j,N,t}, I_{k,t}, \theta_{C,P}, \theta_{N,P}, \eta_{k,t} \right) \\ &= \tilde{f}_{k,s,j} \left( g_{C,j} \left( \theta_{C,t} \right), g_{N,j} \left( \theta_{N,t} \right), I_{k,t}, \theta_{C,P}, \theta_{N,P}, \eta_{k,t} \right) \\ &= g_{k,j} \left( f_{k,s} \left( g_{C,j}^{-1} \left( g_{C,j} \left( \theta_{C,t} \right) \right), g_{N,j}^{-1} \left( g_{N,j} \left( \theta_{N,t} \right) \right), I_{k,t}, \theta_{C,P}, \theta_{N,P}, \eta_{k,t} \right) \right) \\ &= g_{k,j} \left( f_{k,s} \left( \theta_{C,t}, \theta_{N,t}, I_{k,t}, \theta_{C,P}, \theta_{N,P}, \eta_{k,t} \right) \right) \\ &= g_{k,j} \left( \theta_{k,t+1} \right) = \tilde{\theta}_{k,j,t+1}, \end{split}$$

as desired.

It is straightforward to show that

$$\begin{split} &\tilde{f}_{k,s,j} \left( \tilde{\theta}_{j,C,t}, \tilde{\theta}_{j,N,t}, I_{k,t}, \theta_{C,P}, \theta_{N,P}, \eta_{k,t} \right) \\ &= \tilde{f}_{k,s,j} \left( g_{C,j} \left( \theta_{C,t} \right), g_{N,j} \left( \theta_{N,t} \right), I_{k,t}, \theta_{C,P}, \theta_{N,P}, \eta_{k,t} \right) \\ &= g_{k,j} \left( f_{k,s} \left( g_{C,j}^{-1} \left( g_{C,j} \left( \theta_{C,t} \right) \right), g_{N,j}^{-1} \left( g_{N,j} \left( \theta_{N,t} \right) \right), I_{k,t}, \theta_{C,P}, \theta_{N,P}, \eta_{k,t} \right) \right) \\ &= g_{k,j} \left( f_{k,s} \left( \theta_{C,t}, \theta_{N,t}, I_{k,t}, \theta_{C,P}, \theta_{N,P}, \eta_{k,t} \right) \right) \\ &= g_{k,j} \left( \theta_{k,t+1} \right) = \tilde{\theta}_{k,j,t+1}, \end{split}$$

as desired.

• Hence,  $\tilde{f}_{k,s,j}$  is the equation of motion for the anchored skills  $\tilde{\theta}_{k,j,t+1}$  that is consistent with the equation of motion  $f_{k,s}$  for the original skills  $\theta_{k,t}$ .



• Thus far, we have maintained the assumption that the error term  $\eta_{k,t}$  in the technology (1) is independent of all the other inputs  $(\theta_t, I_{k,t}, \theta_P)$  as well as  $\eta_{\ell,t}, k \neq \ell$ .

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- This implies that variables not observed by the econometrician are not used by parents to make their decisions regarding investments  $I_{k,t}$ .
- This is a very strong assumption.
- The availability of data on adult outcomes can be exploited to relax this assumption and allow for endogeneity of the inputs.



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- We can then write outcomes as functions of T+1 skills as well as unobserved (by the economist) time-invariant heterogeneity component,  $\pi$ , on which parents make their investment decisions:

$$Z_{4,j} = \alpha_{4,C,j}\theta_{C,T+1} + \alpha_{4,N,j}\theta_{N,T+1} + \alpha_{4,\pi,j}\pi + \varepsilon_{4,j},$$
 for  $j \in \{1, 2, \dots, J\}$ .

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 for  $j \in \{1, 2, \dots, J\}$ .

• We can use the analysis previously discussed, suitably extended to allow for measurements  $Z_{4,j}$ , to secure identification of the factor loadings  $\alpha_{4,C,j}$ ,  $\alpha_{4,N,j}$ , and  $\alpha_{4,\pi,j}$ .

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- We can apply the argument to secure identification of the joint distribution of  $(\theta_t, I_t, \theta_P, \pi)$ .
- Write  $\eta_{k,t} = (\pi, \nu_{k,t})$ .



• Extending the preceding analysis, we can identify a more general version of the technology:

$$\theta_{k,t+1} = f_{k,s} \left( \theta_t, I_{k,t}, \theta_P, \pi, \nu_{k,t} \right).$$

 $\pi$  is permitted to be correlated with the inputs  $(\theta_t, I_t, \theta_P)$  and  $\nu_{k,t}$  is assumed to be independent from the vector  $(\theta_t, I_t, \theta_P, \pi)$ as well as  $\nu_{l,t}$  for  $l \neq k$ .

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• The next subsection develops a more general approach that allows  $\pi$  to vary over time.

 This subsection relaxes the invariant heterogeneity assumption by using exclusion restrictions based on economic theory to identify the technology under more general conditions.

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- $\pi_t$  evolves over time and agents make investment decisions based on it.
- Define  $y_t$  as family resources in period t (e.g., income, assets, constraints).
- We assume that suitable multiple measurements of  $\left(\theta_P, \left\{\theta_t, I_{C,t}, I_{N,t}, y_t\right\}_{t=1}^T\right)$  are available to identify their (joint) distribution.



• In our application, we assume that  $y_t$  is measured without error We further assume that the error term  $\eta_{k,t}$  can be decomposed into two components:  $(\pi_t, \nu_{k,t})$  so that we may write the technology as

$$\theta_{k,t+1} = f_{k,s} \left( \theta_t, I_{k,t}, \theta_P, \pi_t, \nu_{k,t} \right). \tag{17}$$

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 $\pi_t$  is assumed to be a scalar shock independent over people but not over time.

 A common shock affects all technologies, but its effect may differ across technologies. • The component  $\nu_{k,t}$  is independent of  $\theta_t, I_{k,t}, \theta_P, y_t$  and independent of  $\nu_{k,t'}$  for  $t' \neq t$ .

- The component  $\nu_{k,t}$  is independent of  $\theta_t$ ,  $I_{k,t}$ ,  $\theta_P$ ,  $y_t$  and independent of  $\nu_{k,t'}$  for  $t' \neq t$ .
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- Its realization takes place at the end of period t, after investment choices have already been made and implemented.
- The shock  $\pi_t$  is realized before parents make investment choices, so we expect  $I_{k,t}$  to respond to it.
- $\pi_t$  is an innovation that is common to both production functions for skills, although it may have different effects on each.

• We analyze a model of investment of the form

$$I_{k,t} = q_{k,t}(\theta_t, \theta_P, y_t, \pi_t), \ k \in \{C, N\}, t \in \{1, \dots, T\}.$$
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• Equation (18) is the investment policy function that maps state variables for the parents,  $(\theta_t, \theta_P, y_t, \pi_t)$ , to the control variables  $I_{k,t}$  for  $k \in \{C, N\}$ .

• Our analysis relies on the assumption that the disturbances  $\pi_t$  and  $\nu_{k,t}$  in Equation (17) are both scalar, although all other variables may be vector-valued.

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- If the disturbances  $\pi_t$  are *i.i.d.*, identification is straightforward.
- To see this, impose an innocuous normalization (e.g., assume a specific marginal distribution for  $\pi_t$ ).
- Then, the relationship  $I_{k,t} = q_{k,t} (\theta_t, \theta_P, y_t, \pi_t)$  can be identified, provided, for instance, that  $\pi_t$  is independent from  $(\theta_t, \theta_P, y_t)$ .

References

Introduction

• If  $\pi_t$  is serially correlated, it is not plausible to assume independence between  $\pi_t$  and  $\theta_t$ , because past values of  $\pi_t$  will have an impact on both current  $\pi_t$  and on current  $\theta_t$  (via the effect of past  $\pi_t$  on past  $I_{k,t}$ ).

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- To address this problem, lagged values of income  $y_t$  can be used as instruments for  $\theta_t$  ( $\theta_P$  and  $y_t$  could serve as their own instruments).
- This approach works if  $\pi_t$  is independent of  $\theta_P$  as well as past and present values of  $y_t$ .
- After normalization of the distribution of the disturbance  $\pi_t$ , the general nonseparable function  $q_t$  can be identified using quantile instrumental variable techniques (Chernozhukov et al., 2007), under standard assumptions in that literature, including monotonicity and completeness.

• Once the functions  $q_{k,t}$  have been identified, one can obtain  $q_{k,t}^{-1}\left(\theta_t,\theta_P,y_t,I_{k,t}\right)$ , the inverse of  $q_{k,t}\left(\theta_t,\theta_P,y_t,\pi_t\right)$  with respect to its last argument, provided  $q_{k,t}\left(\theta_t,\theta_P,y_t,\pi_t\right)$  is strictly monotone in  $\pi_t$  at all values of the arguments.

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- We can then rewrite the technology function (18) as:

$$\theta_{k,t+1} = f_{k,s} \left( \theta_t, I_{k,t}, \theta_P, q_{k,t}^{-1} \left( \theta_t, \theta_P, y_t, I_{k,t} \right), \nu_{k,t} \right)$$

$$\equiv f_{k,s}^{\text{rf}} \left( \theta_t, I_{k,t}, \theta_P, y_t, \nu_{k,t} \right).$$

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• Instruments are unnecessary here, because the disturbance  $\nu_{k,t}$  is assumed independent from all other variables.

• However, to identify the technology  $f_{k,s}$ , we need to disentangle the direct effect of  $\theta_t, I_{k,t}, \theta_P$  on  $\theta_{t+1}$  from their indirect effect through  $\pi_t = q_{k,t}^{-1}(\theta_t, \theta_P, y_t, I_{k,t})$ .

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- To accomplish this, we exploit our knowledge of  $q_{k,t}^{-1}\left(\theta_{t},\theta_{P},\pi_{t},y_{t}\right)$  to write:

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where, on the right-hand side, we set  $y_t$  such that the corresponding implied value of  $\pi_t$  matches its value on the left-hand side.

• This does not necessarily require  $q_{k,t}^{-1}(\theta_t,\theta_P,y_t,I_{k,t})$  to be invertible with respect to  $y_t$ , since we only need one suitable value of  $y_t$  for each given  $(\theta_t,\theta_P,I_{k,t},\pi_t)$  and do not necessarily require a one-to-one mapping.

• By construction, the support of the distribution of  $y_t$  conditional on  $\theta_t, \theta_P, I_{k,t}$ , is sufficiently large to guarantee the existence of at least one solution because, for a fixed  $\theta_t, I_{k,t}, \theta_P$ , variations in  $\pi_t$  are entirely due to  $y_t$ .

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- We present a more formal discussion of our identification strategy in Section 3.3 of the Web appendix.

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- Next, we replace  $I_{k,t}$  by its value given by the policy function in the technology

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Introduction

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• Eliminating  $I_{k,t}$  solves the endogeneity problem because the two disturbances  $\pi_t$  and  $\nu_{k,t}$  are now independent of all explanatory variables, by assumption.

• We can then write:

$$E \left[\theta_{k,t+1} \middle| \theta_t, \theta_P, y_t \right]$$

$$= \int f_{k,s} \left(\theta_t, q_{k,t} \left(\theta_t, \theta_P, y_t, \pi_t \right), \theta_P, \pi_t, 0\right) f_{\pi_t} \left(\pi_t\right) d\pi_t$$

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• The right-hand is now known up to a vector of parameters  $\beta$  which will be (at least) locally identified if it happens that  $\partial \tilde{f}_{k,s} \left(\theta_t, \theta_P, y_t, \beta\right)/\partial \beta$  evaluated at the true value of  $\beta$  is a vector function of  $\theta_t, \theta_P, y_t$  that is linearly independent.

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- We describe the specific functional forms used in our application.

## **Estimating the Technology of Skill Formation**

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- However, we use parametric maximum likelihood to estimate the model and do not estimate it under the most general conditions.
- We do this for two reasons.
- First, a fully nonparametric approach is too data hungry to apply to samples of the size that we have at our disposal, because the convergence rates of nonparametric estimators are quite slow.

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- Nonetheless, the analysis of this paper shows that in principle the parametric structure used to secure the estimates reported below is not strictly required to identify the technology.

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- Web Appendix 7 discusses how we implement anchoring.
- Section 8 of the Web Appendix reports a limited Monte Carlo study of a version of the general estimation strategy.

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- Starting in 1986, the children of the NLSY/1979 female respondents, ages 0-14, have been assessed every two years.
- The assessments measure cognitive ability, temperament, motor and social development, behavior problems, and self-competence of the children as well as their home environments.

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- Web Appendix Tables 9-1–9-3 present summary statistics of the sample we use.
- We estimate a model for a single child and ignore interactions among children and the allocation decisions over multiple child families.

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- We have eight periods distributed over two stages of development.
- We report estimates of a variety of specifications.



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- They solve several problems in estimating skill formation technologies.
- First, there are many proxies for parental investments in children's cognitive and noncognitive development.
- Using a dynamic factor model, we let the data pick the best combinations of family input measures that predict levels and growth in test scores.

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- Assuming that the data are missing at random, we integrate out the missing items from the sample likelihood.

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- Thus we assume  $I_{C,t} = I_{N,t}$  and define it as  $I_t$ .



**Empirical Specification** 



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- We estimate versions of the technology (3)-(4) augmented to include shocks:

$$\theta_{k,t+1} = \left[ \gamma_{s,k,1} \theta_{C,t}^{\phi_{s,k}} + \gamma_{s,k,2} \theta_{N,t}^{\phi_{s,k}} + \gamma_{s,k,3} I_t^{\phi_{s,k}} + \gamma_{s,k,4} \theta_{C,P}^{\phi_{s,k}} + \gamma_{s,k,5} \theta_{N,P}^{\phi_{s,k}} \right]^{\frac{1}{\phi_{s,k}}} e^{\eta_{k,t+1}},$$
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- We assume that measurements  $Z_{a,k,t,j}$  proxy the *natural* logarithms of the factors.

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- Define the  $t^{\text{th}}$  row of  $\theta$  as  $\theta_t^r$  where r stands for row.

$$\ln \theta_t^r = \left( \ln \theta_{C,t}, \ln \theta_{N,t}, \ln I_t, \ln \theta_{C,P}, \ln \theta_{N,P}, \ln \pi \right).$$

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- Under the second specification,  $\ln \theta_t^r$  is distributed as a mixture of  $\mathcal{T}$  normals.
- Let  $\phi(x; \mu_{t,\tau}, \Sigma_{t,\tau})$  denote the density of a normal random variable with mean  $\mu_{t,\tau}$  and variance-covariance matrix  $\Sigma_{t,\tau}$ .



• The mixture of normals writes the density of  $\ln \theta_t^r$  as

$$p\left(\ln \theta_t^r\right) = \sum_{\tau=1}^{\gamma} \omega_{\tau} \phi\left(\ln \theta_t^r; \mu_{t,\tau}, \Sigma_{t,\tau}\right)$$

subject to: 
$$\sum_{\tau=1}^{\mathcal{T}} \omega_{\tau} = 1$$
 and  $\sum_{\tau=1}^{\mathcal{T}} \omega_{\tau} \mu_{t,\tau} = 0$ .

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- In this paper, we mainly use completed years of education by age 19, a continuous variable, as an anchor.

## **Empirical Estimates**

• This section presents results from an extensive empirical analysis estimating the multistage technology of skill formation accounting for measurement error, non-normality of the factors, endogeneity of inputs and family investment decisions.

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- We first present baseline two stage models that anchor outcomes in terms of their effects on schooling attainment, that correct for measurement errors, and that assume that the factors are normally distributed.

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- These models do not account for endogeneity of inputs through unobserved heterogeneity components or family investment decisions.

 The baseline model is far more general than what is presented in previous research on the formation of child skills that uses unanchored test scores as outcome measures and does not account for measurement error.  We present evidence on the first order empirical importance of measurement error.

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- When we do not correct for it, the estimated technology suggests that there is no effect of early investment on outcomes.
- Controlling for endogeneity of family inputs by accounting for unobserved heterogeneity  $(\pi)$ , and accounting explicitly for family investment decisions has substantial effects on estimated parameters.

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- The cross productivity effect is weaker and less precisely determined in the second stage.
- There is no evidence for a cross productivity effect of cognitive skills on noncognitive skills at either stage.
- The estimated elasticity of substitution for inputs in cognitive skill is substantially lower in the second stage of a child's life cycle than in the first stage.



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- These estimates suggest that it is easier to redress endowment deficits that determine cognition in the first stage of a child's life cycle than in the second stage.
- For socioemotional (noncognitive) skills, the opposite is true.

• For cognitive skills, the productivity parameter associated with parental investment  $(\gamma_{1,C,3})$  is greater in the first stage than in the second stage  $(\gamma_{2,C,3})$ .

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- For noncognitive skills, the pattern of estimates for the productivity parameter across models is less clear cut, but there are not dramatic differences across the stages.
- For both outputs, the parameter associated with the effect of parental noncognitive skills on output is smaller at the second stage than the first stage.

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- For these and other estimated models which are not reported, allowing for nonnormality has only minor effects on the estimates.
- However, anchoring affects the estimates.
- To facilitate computation, we use years of schooling attained as the anchor in all of the models reported in this section of the paper.

## The Baseline Specification

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Introduction Model Identifying Estimating Conclusion References References

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- Noncognitive skills foster cognitive skills in the first stage but not in the second stage.
- Cognitive skills have no cross-productivity effect on noncognitive skills at either stage.



Using the Factor Model to Correct for Measurement Error Linear Anchoring on Educational Attainment (Years of Schooling) No Unobserved Heterogeneity  $(\pi)$ , Factors Normally Distributed The Technology of Cognitive Skill Formation

		First Stage Parameters		Second Stage Parameters
Current Period Cognitive Skills (Self-Productivity)	γ <sub>1,C,1</sub>	0.487	γ <sub>2,C,1</sub>	0.902
		(0.030)		(0.014)
Current Period Noncognitive Skills (Cross-Productivity)	γ <sub>1,C,2</sub>	0.083	γ <sub>2,C,2</sub>	0.011
		(0.026)		(0.005)
Current Period Investments	γ <sub>1,C,3</sub>	0.231	γ <sub>2,C,3</sub>	0.020
		(0.024)		(0.006)
Parental Cognitive Skills	γ <sub>1,C,4</sub>	0.050	γ <sub>2,C,4</sub>	0.047
		(0.013)		(0.008)
Parental Noncognitive Skills	γ <sub>1,C,5</sub>	0.148	γ <sub>2,C,5</sub>	0.020
		(0.030)		(0.010)
Complementarity Parameter	$\phi_{1,C}$	0.611	$\phi_{2,C}$	-1.373
		(0.240)		(0.168)
Implied Elasticity of Substitution	$1/(1-\phi_{1,C})$	2.569	$1/(1-\phi_{2,C})$	0.421
	2		2	
Variance of Shocks $\eta_{c,t}$	$\delta^2_{1,C}$	0.165	$\delta^2_{2,C}$	0.097
		(0.007)		(0.003)

### The Technology of Noncognitive Skill Formation

		First Stage Parameters		Second Stage Parameters
Current Period Cognitive Skills (Cross-Productivity)	$\gamma_{1,N,1}$	0.000	$\gamma_{2,N,1}$	0.008
		(0.025)		0.010
Current Period Noncognitive Skills (Self-Productivity)	$\gamma_{1,N,2}$	0.649	γ <sub>2,N,2</sub>	0.868
		(0.034)		0.011
Current Period Investments	$\gamma_{1,N,3}$	0.146	$\gamma_{2,N,3}$	0.055
		(0.027)		0.013
Parental Cognitive Skills	$\gamma_{1,N,4}$	0.022	$\gamma_{2,N,4}$	0.000
		(0.011)		0.007
Parental Noncognitive Skills	$\gamma_{1,N,5}$	0.183	$\gamma_{2,N,5}$	0.069
		(0.031)		0.017
Complementarity Parameter	$\phi_{1,N}$	-0.674	$\phi_{2,N}$	-0.695
		(0.324)		0.274
Implied Elasticity of Substitution	$1/(1-\phi_{1,N})$	0.597	$1/(1-\phi_{2,N})$	0.590
Variance of Shocks $\eta_{n,t}$	$\delta^2_{1,N}$	0.189	$\delta^2_{2,N}$	0.103
		(0.012)		0.004

Note: Standard errors in parenthesis



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- The productivity parameter for investment is greater in the first period than the second period for either skill.
- The difference across stages in the estimated parameters is dramatic for cognitive skills.
- The variability in the shocks is greater in the second period than in the first period.
- The elasticity of substitution for cognitive skills is much greater in the first period than in the second period.
- However, the estimated elasticity of substitution for noncognitive skills increases slightly in the second stage.



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- In producing noncognitive skills, parental cognitive skills play no role at either stage.
- Parental noncognitive skills play a strong role in stage 1 and a weaker role in stage 2.

The Empirical Importance of Measurement Error

 Using our factor model, we can investigate the extent of measurement error on each measure of skill and investment in our data.

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- To simplify the notation, we keep the conditioning on the regressors implicit and, without loss of generality, consider the measurements on cognitive skills in period t.
- For linear measurement systems, the variance can be decomposed as follows:

$$Var(Z_{1,C,t,j}) = \alpha_{1,C,t,j}^2 Var(\ln \theta_{C,t}) + Var(\varepsilon_{1,C,t,j}).$$



Introduction

• The fractions of the variance of  $Z_{1,C,t,j}$  due to measurement error,  $s_{1,C,t,j}^{\varepsilon}$ , and true signal,  $s_{1,C,t,j}^{\theta}$  are, respectively,

$$s_{1,C,t,j}^{\varepsilon} = \frac{Var\left(\varepsilon_{1,C,t,j}\right)}{\alpha_{1,C,t,j}^{2} Var\left(\ln \theta_{C,t}\right) + Var\left(\varepsilon_{1,C,t,j}\right)} \text{ (noise)}$$

and

$$s_{1,C,t,j}^{\theta} = \frac{\alpha_{1,C,t,j}^{2} Var\left(\ln \theta_{C,t}\right)}{\alpha_{1,C,t,j}^{2} Var\left(\ln \theta_{C,t}\right) + Var\left(\varepsilon_{1,C,t,j}\right)} \text{ (signal)}.$$

• For each measure of skill and investment used in the estimation, we construct  $s_{1,C,t,j}^{\varepsilon}$  and  $s_{1,C,t,j}^{\theta}$  which are reported in Table 2A.

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- The proxy with the highest signal ratio is the PIAT Reading Recognition Scores at ages 5-6, for which almost 96% of the observed variance is due to the variance of the true signal.
- Overall, about 54% of the observed variance is associated with the cognitive skill factors  $\theta_{C,t}$ .



#### Percentage of Total Variance in Measurements due to Signal and Noise

Measurement of Child's Cognitive Skills	%Signal	%Noise	Measurement of Child's Noncognitive Skills	%Signal	%Noise
Gestation Length	0.501	0.499	Difficulty at Birth	0.151	0.849
Weight at Birth	0.557	0.443	Friendliness at Birth	0.165	0.835
Motor-Social Development at Birth	0.045	0.955	Compliance at Ages 1-2	0.232	0.768
Motor-Social Development at Ages 1-2	0.275	0.725	Insecure at Ages 1-2	0.080	0.920
Body Parts at Ages 1-2	0.308	0.692	Sociability at Ages 1-2	0.075	0.925
Memory for Locations at Ages 1-2	0.160	0.840	Difficulty at Ages 1-2	0.382	0.618
Motor-Social Development at Ages 3-4	0.410	0.590	Friendliness at Ages 1-2	0.189	0.811
Picture Vocabulary at Ages 3-4	0.431	0.569	Compliance at Ages 3-4	0.133	0.867
Picture Vocabulary at Ages 5-6	0.225	0.775	Insecure at Ages 3-4	0.122	0.878
PIAT-Mathematics at Ages 5-6	0.314	0.686	Sociability at Ages 3-4	0.008	0.992
PIAT-Reading Recognition at Ages 5-6	0.958	0.042	Behavior Problem Index Antisocial at Ages 3-4	0.405	0.595
PIAT-Reading Comprehension at Ages 5-6	0.938	0.062	Behavior Problem Index Anxiety at Ages 3-4	0.427	0.573
PIAT-Mathematics at Ages 7-8	0.465	0.535	Behavior Problem Index Headstrong at Ages 3-4	0.518	0.482
PIAT-Reading Recognition at Ages 7-8	0.869	0.131	Behavior Problem Index Hyperactive at Ages 3-4	0.358	0.642
PIAT-Reading Comprehension at Ages 7-8	0.797	0.203	Behavior Problem Index Conflict at Ages 3-4	0.336	0.664
PIAT-Mathematics at Ages 9-10	0.492	0.508	Behavior Problem Index Antisocial at Ages 5-6	0.435	0.565
PIAT-Reading Recognition at Ages 9-10	0.817	0.183	Behavior Problem Index Anxiety at Ages 5-6	0.409	0.591
PIAT-Reading Comprehension at Ages 9-10	0.666	0.334	Behavior Problem Index Headstrong at Ages 5-6	0.611	0.389
PIAT-Mathematics at Ages 11-12	0.516	0.484	Behavior Problem Index Hyperactive at Ages 5-6	0.481	0.519
PIAT-Reading Recognition at Ages 11-12	0.781	0.219	Behavior Problem Index Conflict at Ages 5-6	0.290	0.710
PIAT-Reading Comprehension at Ages 11-12	0.614	0.386	Behavior Problem Index Antisocial Ages 7-8	0.446	0.554
PIAT-Mathematics at Ages 13-14	0.537	0.463	Behavior Problem Index Anxiety Ages 7-8	0.475	0.525
PIAT-Reading Recognition at Ages 13-14	0.735	0.265	Behavior Problem Index Headstrong Ages 7-8	0.605	0.395
PIAT-Reading Comprehension at Ages 13-14	0.549	0.451	Behavior Problem Index Hyperactive Ages 7-8	0.497	0.503



Measurement of Maternal Cognitive Skills			Behavior Problem Index Conflict Ages 7-8	0.327	0.673
ASVAB Arithmetic Reasoning	0.728	0.272	Behavior Problem Index Antisocial Ages 9-10	0.503	0.497
ASVAB Word Knowledge	0.625	0.375	Behavior Problem Index Anxiety Ages 9-10	0.472	0.528
ASVAB Paragraph Composition	0.576	0.424	Behavior Problem Index Headstrong Ages 9-10	0.577	0.423
ASVAB Numerical Operations	0.461	0.539	Behavior Problem Index Hyperactive Ages 9-10	0.463	0.537
ASVAB Coding Speed	0.353	0.647	Behavior Problem Index Conflict Ages 9-10	0.369	0.631
ASVAB Mathematical Knowledge	0.662	0.338	Behavior Problem Index Antisocial Ages 11-12	0.514	0.486
Measurement of Maternal Noncognitive Skills			Behavior Problem Index Anxiety Ages 11-12	0.500	0.500
Self-Esteem "I am a person of worth"	0.277	0.723	Behavior Problem Index Headstrong Ages 11-12	0.603	0.397
Self-Esteem " I have good qualities"	0.349	0.651	Behavior Problem Index Hyperactive Ages 11-12	0.505	0.495
Self-Esteem "I am a failure"	0.444	0.556	Behavior Problem Index Conflict Ages 11-12	0.370	0.630
Self-Esteem "I have nothing to be proud of"	0.375	0.625	Behavior Problem Index Antisocial Ages 13-14	0.494	0.506
Self-Esteem "I have a positive attitude"	0.406	0.594	Behavior Problem Index Anxiety Ages 13-14	0.546	0.454
Self-Esteem "I wish I had more self-respect"	0.341	0.659	Behavior Problem Index Headstrong Ages 13-14	0.595	0.405
Self-Esteem "I feel useless at times"	0.293	0.707	Behavior Problem Index Hyperactive Ages 13-14	0.525	0.475
Self-Esteem "I sometimes think I am no good"	0.375	0.625	Behavior Problem Index Conflict Ages 13-14	0.414	0.586
Locus of Control "I have no control"	0.047	0.953			
Locus of Control "I make no plans for the future"	0.064	0.936			
Locus of Control "Luck is big factor in life"	0.041	0.959			
Locus of Control "Luck plays big role in my life"	0.020	0.980			

### Table 2B

Percentage of Total Variance in Measurements due to Signal and Noise							
Measurements of Parental Investments	%Signal	%Noise	Measurements of Parental Investments	%Signal	%Noise		
How Often Child Goes on Outings during Year of Birth	0.329	0.671	Child Has Musical Instruments Ages 7-8	0.022	0.978		
Number of Books Child Has during Year of Birth	0.209	0.791	Family Subscribes to Daily Newspapers Ages 7-8	0.023	0.977		
How Often Mom Reads to Child during Year of Birth	0.484	0.516	Child Has Special Lessons Ages 7-8	0.018	0.982		
Number of Soft Toys Child Has during Year of Birth	0.126	0.874	How Often Child Goes to Musical Shows Ages 7-8	0.266	0.734		
Number of Push/Pull Toys Child Has during Year of Birth	0.019	0.981	How Often Child Attends Family Gatherings Ages 7-8	0.125	0.875		
How Often Child Eats with Mom/Dad during Year of Birth	0.511	0.489	How Often Child is Praised Ages 7-8	0.046	0.954		
How Often Mom Calls from Work during Year of Birth	0.119	0.881	How Often Child Gets Positive Encouragement Ages 7-8	0.053	0.947		
How Often Child Goes on Outings at Ages 1-2	0.148	0.852	Number of Books Child Has Ages 9-10	0.013	0.987		
Number of Books Child Has Ages 1-2	0.055	0.945	Mom Reads to Child Ages 9-10	0.137	0.863		
How Often Mom Reads to Child Ages 1-2	0.186	0.814	Eats with Mom/Dad Ages 9-10	0.162	0.838		
Number of Soft Toys Child Has Ages 1-2	0.240	0.760	How Often Child Goes to Museum Ages 9-10	0.219	0.781		
Number of Push/Pull Toys Child Has Ages 1-2	0.046	0.954	Child Has Musical Instruments Ages 9-10	0.019	0.981		
How Often Child Eats with Mom/Dad Ages 1-2	0.194	0.806	Family Subscribes to Daily Newspapers Ages 9-10	0.019	0.981		
Mom Calls from Work Ages 1-2	0.070	0.930	Child Has Special Lessons Ages 9-10	0.015	0.985		
How Often Child Goes on Outings Ages 3-4	0.123	0.877	How Often Child Goes to Musical Shows Ages 9-10	0.242	0.758		
Number of Books Child Has Ages 3-4	0.012	0.988	How Often Child Attends Family Gatherings Ages 9-10	0.115	0.885		
How Often Mom Reads to Child Ages 3-4	0.088	0.912	How Often Child is Praised Ages 9-10	0.036	0.964		
How Often Child Eats with Mom/Dad Ages 3-4	0.170	0.830	How Often Child Gets Positive Encouragement Ages 9-10	0.041	0.959		

Number of Magazines at Home Ages 3-4	0.193	0.807	Number of Books Child Has Ages 11-12	0.016	0.984
Child Has a CD player Ages 3-4	0.021	0.979	Eats with Mom/Dad Ages 11-12	0.153	0.847
How Often Child Goes on Outings Ages 5-6	0.100	0.900	How Often Child Goes to Museum Ages 11-12	0.217	0.783
Number of Books Child Has Ages 5-6	0.009	0.991	Child Has Musical Instruments Ages 11-12	0.016	0.984
How Often Mom Reads to Child Ages 5-6	0.086	0.914	Family Subscribes to Daily Newspapers Ages 11-12	0.018	0.982
How Often Child Eats with Mom/Dad Ages 5-6	0.173	0.827	Child Has Special Lessons Ages 11-12	0.013	0.987
Number of Magazines at Home Ages 5-6	0.164	0.836	How Often Child Goes to Musical Shows Ages 11-12	0.225	0.775
Child Has CD player Ages 5-6	0.015	0.985	How Often Child Attends Family Gatherings Ages 11-12	0.103	0.897
How Often Child Goes to Museum Ages 5-6	0.296	0.704	How Often Child is Praised Ages 11-12	0.026	0.974
Child Has Musical Instruments Ages 5-6	0.026	0.974	How Often Child Gets Positive Encouragement Ages 11-12	0.037	0.963
Family Subscribes to Daily Newspapers Ages 5-6	0.025	0.975	Number of Books Child Has Ages 13-14	0.023	0.977
Child Has Special Lessons Ages 5-6	0.020	0.980	Eats with Mom/Dad Ages 13-14	0.152	0.848
How Often Child Goes to Musical Shows Ages 5-6	0.304	0.696	How Often Child Goes to Museum Ages 13-14	0.201	0.799
How Often Child Attends Family Gatherings Ages 5-6	0.141	0.859	Child Has Musical Instruments Ages 13-14	0.015	0.985
How Often Child is Praised Ages 5-6	0.056	0.944	Family Subscribes to Daily Newspapers Ages 13-14	0.017	0.983
How Often Child Gets Positive Encouragement Ages 5-6	0.081	0.919	Child Has Special Lessons Ages 13-14	0.012	0.988
Number of Books Child Has Ages 7-8	0.007	0.993	How Often Child Goes to Musical Shows Ages 13-14	0.224	0.776
How Often Mom Reads to Child Ages 7-8	0.113	0.887	How Often Child Attends Family Gatherings Ages 13-14	0.099	0.901
How Often Child Eats with Mom/Dad Ages 7-8	0.166	0.834	How Often Child is Praised Ages 13-14	0.031	0.969
How Often Child Goes to Museum Ages 7-8	0.240	0.760	How Often Child Gets Positive Encouragement Ages 13-14	0.032	0.968

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- The measures of noncognitive skills tend to be lower in informational content than their cognitive counterparts.
- Overall, less than 40% of the observed variance is due to the variance associated with the factors for noncognitive skills.
- The poorest measure for noncognitive skills is the "Sociability" measure at ages 3-4, in which less than 1% of the observed variance is signal.

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- The measures of noncognitive skills tend to be lower in informational content than their cognitive counterparts.
- Overall, less than 40% of the observed variance is due to the variance associated with the factors for noncognitive skills.
- The poorest measure for noncognitive skills is the "Sociability" measure at ages 3-4, in which less than 1% of the observed variance is signal.
- The richest is the "BPI Headstrong" score, in which almost 62% of the observed variance is due to the variance of the signal.

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- Table 2A also presents the signal-noise ratio of measures of parental cognitive and noncognitive skills.
- Overall, measures of maternal cognitive skills tend to have a higher information content than measures of noncognitive skills.
- While the poorest measurement on cognitive skills has a signal ratio of almost 35%, the richest measurements on noncognitive skills are slightly above 40%.

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- Investment measures are much noisier than either measure of skill.
- The measures for investments at earlier stages tend to be noisier than the measures at later stages.
- It is interesting to note that the measure "Number of Books" has a high signal-noise ratio at early years, but not in later years.
- At earlier years, the measure "How Often Mom Reads to the Child" has about the same informational content as "Number of Books." In later years, measures such as "Trips to the Museum" and "Attendance of Musical Performances" have higher signal-noise ratios.



 These estimates suggest that it is likely to be empirically important to control for measurement error in estimating technologies of skill formation.

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- A general pattern is that at early ages measures of skill tend to be riddled with measurement error, while the reverse is true for the measurement errors for the proxies for investment.

The Effect of Ignoring Measurement Error on the Estimated Technology



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- To make the most convincing case for the importance of measurement error, we use the least error prone proxies as determined in our estimates of Table 2.
- We continue to assume no heterogeneity.



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- In the second stage, the estimated investment effects are generally stronger.
- Unlike all of the specifications that control for measurement error, we estimate strong cross productivity effects of cognitive skills on noncognitive skill production.
- As in Table 1, there are cross productivity effects of noncognitive skills on cognitive skills at both stages although the estimated productivity parameters are somewhat smaller.

The Technology for Cognitive and Noncognitive Skill Formation

Not Correcting for Measurement Error

Linear Anchoring on Educational Attainment (Years of Schooling)

No Unobserved Heterogeneity ( $\pi$ ), Factors Normally Distributed

Panel A: Technology of Cognitive Skill Formation (Next Period Cognitive Skills)

		First Stage Parameters		Second Stage Parameters
Current Period Cognitive Skills (Self-Productivity)	γ <sub>1,C,1</sub>	0.403	γ <sub>2,C,1</sub>	0.657
		(0.058)		(0.013)
Current Period Noncognitive Skills (Cross-Productivity)	γ <sub>1,C,2</sub>	0.218	γ <sub>2,C,2</sub>	0.009
		(0.105)		(0.005)
Current Period Investments	γ <sub>1,C,3</sub>	0.067	γ <sub>2,C,3</sub>	0.167
		(0.090)		(0.018)
Parental Cognitive Skills	γ <sub>1,C,4</sub>	0.268	γ <sub>2,C,4</sub>	0.047
		(0.078)		(0.009)
Parental Noncognitive Skills	γ <sub>1,C,5</sub>	0.044	γ <sub>2,C,5</sub>	0.119
		(0.050)		(0.150)
Complementarity Parameter	$\phi_{1,C}$	0.375	$\phi_{2,C}$	-0.827
		(0.294)		(0.093)
Implied Elasticity of Substitution	$1/(1-\phi_{1,C})$	1.601	$1/(1-\phi_{2,C})$	0.547
Variance of Shocks $\eta_{C,t}$	$\delta^2_{1,C}$	0.941	$\delta^2_{2,C}$	0.358
		(0.048)	) + 4 (F) + 4	= (0.006)

Panel B: Technology of Noncognitive Skill Formation (Next Period Noncognitive Skills)

		First Stage Parameters		Second Stage Parameters
Current Period Cognitive Skills (Cross-Productivity)	$\gamma_{1,N,1}$	0.193	$\gamma_{2,N,1}$	0.058
		(0.095)		(0.014)
Current Period Noncognitive Skills (Self-Productivity)	$\gamma_{1,N,2}$	0.594	$\gamma_{2,N,2}$	0.638
		(0.090)		(0.020)
Current Period Investments	$\gamma_{1,N,3}$	0.099	$\gamma_{2,N,3}$	0.239
		(0.296)		(0.031)
Parental Cognitive Skills	$\gamma_{1,N,4}$	0.114	$\gamma_{2,N,4}$	0.065
		(0.055)		(0.015)
Parental Noncognitive Skills	$\gamma_{1,N,5}$	0.000	$\gamma_{2,N,5}$	0.000
		(0.821)		(0.203)
Complementarity Parameter	$\phi_{1,N}$	-0.723	$\phi_{2,N}$	-0.716
		(0.441)		(0.127)
Implied Elasticity of Substitution	$1/(1-\phi_{1,N})$	0.580	$1/(1-\phi_{2,N})$	0.583
Variance of Shocks $\eta_{N,t}$	$\delta^2_{1,N}$	0.767	$\delta^2_{2,N}$	0.597
		(0.076)		(0.017)

Note: Standard errors in parenthesis



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- The elasticities of substitution for noncognitive skills are substantially lower at both stages in the specification that does not control for measurement error.
- The error variances of the shocks are substantially larger.
- Parental cognitive skills are estimated to have substantial effects on childhood cognitive skills but not their noncognitive skills.
- This contrasts with the estimates reported in Table 1 that show strong effects of parental noncognitive skills on childhood cognitive skills in both stages, and on noncognitive skills in the first stage.



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- $\bullet$  error term  $\nu_{k,t}$  that is assumed to be uncorrelated with all other variables.

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- The coefficient on parental investment in the first stage is  $\gamma_{1,C,3} \cong 0.16$ , while in the second stage  $\gamma_{2,C,3} \cong 0.04$ .

- Table 4 shows that correcting for heterogeneity, the estimated coefficients for parental investments have a greater impact on cognitive skills at the first stage.
- The coefficient on parental investment in the first stage is  $\gamma_{1,C,3}\cong 0.16$ , while in the second stage  $\gamma_{2,C,3}\cong 0.04$ .
- The elasticity of substitution in the first stage is well above one,  $\sigma_{1,C} = \frac{1}{1-0.31} \cong 1.45$ , and in the second stage it is well below one,  $\sigma_{2,C} \cong \frac{1}{1+1.24} \cong 0.44$ .

The Technology for Cognitive and Noncognitive Skill Formation
Linear Anchoring on Educational Attainment (Years of Schooling)
Allowing for Unobserved Heterogeneity (π), Factors Normally Distributed
Panel A: Technology of Cognitive Skill Formation (Next Period Cognitive Skills)

		First Stage Parameters	,	Second Stage Parameters
Current Period Cognitive Skills (Self-Productivity)	$\gamma_{1,C,1}$	0.479	γ <sub>2,C,1</sub>	0.831
		(0.026)		(0.011)
Current Period Noncognitive Skills (Cross-Productivity)	γ <sub>1,C,2</sub>	0.070	γ <sub>2,C,2</sub>	0.001
		(0.024)		(0.005)
Current Period Investments	γ <sub>1,C,3</sub>	0.161	γ <sub>2,C,3</sub>	0.044
		(0.015)		(0.006)
Parental Cognitive Skills	γ <sub>1,C,4</sub>	0.031	$\gamma_{2,C,4}$	0.073
		(0.013)		(0.008)
Parental Noncognitive Skills	$\gamma_{1,C,5}$	0.258	γ <sub>2,C,5</sub>	0.051
		(0.029)		(0.014)
Complementarity Parameter	$\phi_{1,C}$	0.313	$\phi_{2,C}$	-1.243
		(0.134)		(0.125)
Implied Elasticity of Substitution	$1/(1-\phi_{1,C})$	1.457	$1/(1-\phi_{2,C})$	0.446
Variance of Shocks $\eta_{C,t}$	$\delta^2_{\ 1,C}$	0.176	$\delta^2_{2,C}$	0.087
		(0.007)		(0.003)

Panel B: Technology of Noncognitive Skill Formation (Next Period Noncognitive Skills)

	`	First Stage Parameters	5	Second Stage Parameters
Current Period Cognitive Skills (Cross-Productivity)	$\gamma_{1,N,1}$	0.000	$\gamma_{2,N,1}$	0.000
		(0.026)		(0.010)
Current Period Noncognitive Skills (Self-Productivity)	$\gamma_{1,N,2}$	0.585	γ <sub>2,N,2</sub>	0.816
		(0.032)		(0.013)
Current Period Investments	$\gamma_{1,N,3}$	0.065	γ <sub>2,N,3</sub>	0.051
		(0.021)		(0.006)
Parental Cognitive Skills	$\gamma_{1,N,4}$	0.017	$\gamma_{2,N,4}$	0.000
		(0.013)		(0.008)
Parental Noncognitive Skills	$\gamma_{1,N,5}$	0.333	$\gamma_{2,N,5}$	0.133
		(0.034)		(0.017)
Complementarity Parameter	$\phi_{1,N}$	-0.610	$\phi_{2,N}$	-0.551
		(0.215)		(0.169)
Implied Elasticity of Substitution	$1/(1-\phi_{1,N})$	0.621	$1/(1-\phi_{2,N})$	0.645
Variance of Shocks $\eta_{N,t}$	$\delta^2_{1,N}$	0.222	$\delta^2_{2,N}$	0.101
		(0.013)		(0.004)

Note: Standard errors in parenthesis



• These estimates are statistically significantly different from each other and from the estimates of the elasticities of substitution  $\sigma_{1,N}$  and  $\sigma_{2,N}$ .

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- Consistent with the estimates reported in Table 1, noncognitive skills increase cognitive skills in the first stage, but not in the second stage.
- Parental cognitive and noncognitive skills affect the accumulation of childhood cognitive skills.

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- Panel B of Table 4 presents estimates of the technology of noncognitive skills.
- Note that, contrary to the estimates reported for the technology for cognitive skills, the elasticity of substitution increases slightly from the first stage to the second stage.
- For the early stage,  $\sigma_{1,N}\cong 0.62$  while for the late stage,  $\sigma_{2,N}\cong 0.65$ .
- However, the elasticity is about 50% higher for investments in noncognitive skills for the late stage in comparison to the elasticity for investments in cognitive skills.

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- Parental noncognitive skills affect the accumulation of a child's noncognitive skills both in early and late periods, but the same is not true for parental cognitive skills.
- The estimates in Table 4 show a strong effect of parental cognitive skills on either stage of the production of noncognitive skills.

A More General Approach to Solving the Problem of the Endogeneity of Inputs

 This section relaxes the invariant heterogeneity assumption and reports empirical results from a more general model of time-varying heterogeneity.

## A More General Approach to Solving the Problem of the Endogeneity of Inputs

- This section relaxes the invariant heterogeneity assumption and reports empirical results from a more general model of time-varying heterogeneity.
- Our approach to estimation is motivated by the general analysis, but, in the interest of computational tractability, we make parametric and distributional assumptions.

• We augment the measurement system (8)–(10) by investment equation (18), which is motivated by economic theory.

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- Our investment equation is

$$I_{t} = k_{C}\theta_{C,t} + k_{N}\theta_{N,t} + k_{C,P}\theta_{C,P} + k_{N,P}\theta_{N,P} + k_{v}y_{t} + \pi_{t}.$$
 (20)



References

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- We specify the income process as

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• We assume that  $\nu_{y,t} \perp \!\!\! \perp (\theta_{t'}, \nu_{y,t'})$  for all  $t' \neq t$  and  $\nu_{y,t} \perp \!\!\! \perp (y_{t'}, \nu_{k,t}, \theta_P)$ , t > t',  $k \in \{C, N\}$ , where " $\perp$ " means independence.



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- We further assume that  $\nu_{\pi,t} \perp \!\!\! \perp (\theta_{t'}, \theta_p, \nu_{k,t'})$  and that  $(\theta_1, y_1) \perp \!\!\! \perp \pi$ .



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- In addition,  $\nu_{y,t} \sim N\left(0, \sigma_{y}^{2}\right)$  and  $\nu_{\pi,t} \sim N\left(0, \sigma_{\pi}^{2}\right)$ .



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- We further assume that  $\nu_{\pi,t} \perp \!\!\! \perp (\theta_{t'}, \theta_{p}, \nu_{k,t'})$  and that  $(\theta_1, y_1) \perp \!\!\! \perp \pi$ .
- In addition,  $\nu_{y,t} \sim N\left(0, \sigma_{v}^{2}\right)$  and  $\nu_{\pi,t} \sim N\left(0, \sigma_{\pi}^{2}\right)$ .
- In Web Appendix 8, we report favorable results from a Monte Carlo study of the estimator based on these assumptions.

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- Estimates of the parameters of  $q_{k,t}$  are presented in Web Appendix 10.
- We also report estimates of the anchoring equation and other outcome equations in that appendix.

## The Technology for Cognitive and Noncognitive Skill Formation Estimated Along with Investment Equation with

Linear Anchoring on Educational Attainment (Years of Schooling), Factors Normally Distributed
Panel A: Technology of Cognitive Skill Formation (Next Period Cognitive Skills)

<i>., .</i>	`	First Stage Parameters	,	Second Stage Parameters
Current Period Cognitive Skills (Self-Productivity)	γ <sub>1,C,1</sub>	0.485	γ <sub>2,C,1</sub>	0.884
		(0.031)		(0.013)
Current Period Noncognitive Skills (Cross-Productivity)	γ <sub>1,C,2</sub>	0.062	γ <sub>2,C,2</sub>	0.011
		(0.026)		(0.005)
Current Period Investments	γ <sub>1,C,3</sub>	0.261	γ <sub>2,C,3</sub>	0.044
		(0.026)		(0.011)
Parental Cognitive Skills	γ <sub>1,C,4</sub>	0.035	γ <sub>2,C,4</sub>	0.051
		(0.015)		(0.008)
Parental Noncognitive Skills	γ <sub>1,C,5</sub>	0.157	γ <sub>2,C,5</sub>	0.011
		(0.033)		(0.012)
Complementarity Parameter	$\phi_{1,C}$	0.585	$\phi_{2,C}$	-1.220
		(0.225)		(0.149)
Implied Elasticity of Substitution	$1/(1-\phi_{1,C})$	2.410	$1/(1-\phi_{2,C})$	0.450
Variance of Shocks $\eta_{C,t}$	$\delta^2_{1,C}$	0.165	$\delta^2_{2,C}$	0.098
		(0.007)		(0.003)

Panel B: Technology of Noncognitive Skill Formation (Next Period Noncognitive Skills)

3	· ·	First Stage Parameters	8	Second Stage Parameters
Current Period Cognitive Skills (Cross-Productivity)	$\gamma_{1,N,1}$	0.000	$\gamma_{2,N,1}$	0.002
		(0.028)		(0.011)
Current Period Noncognitive Skills (Self-Productivity)	$\gamma_{1,N,2}$	0.602	$\gamma_{2,N,2}$	0.857
		(0.034)		(0.011)
Current Period Investments	$\gamma_{1,N,3}$	0.209	γ <sub>2,N,3</sub>	0.104
		(0.031)		(0.022)
Parental Cognitive Skills	$\gamma_{1,N,4}$	0.014	$\gamma_{2,N,4}$	0.000
		(0.013)		(0.008)
Parental Noncognitive Skills	$\gamma_{1,N,5}$	0.175	$\gamma_{2,N,5}$	0.037
		(0.033)		(0.021)
Complementarity Parameter	$\phi_{1,N}$	-0.464	$\phi_{2,N}$	-0.522
		(0.263)		(0.214)
Implied Elasticity of Substitution	$1/(1-\phi_{1,N})$	0.683	$1/(1-\phi_{2,N})$	0.657
Variance of Shocks $\eta_{N,t}$	$\delta^2_{1,N}$	0.203	$\delta^2_{\ 2,N}$	0.102
		(0.012)		(0.003)

Note: Standard errors in parenthesis



• When we introduce an equation for investment, the impact of early investments on the production of cognitive skill increases from  $\gamma_{1,C,3}\cong 0.17$  (see Table 4, Panel A) to  $\gamma_{1,C,3}\cong 0.26$  (see Table 5, Panel A).

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- The estimate of the elasticity of substitution for cognitive skill technology falls slightly from  $\sigma_{2,C}=\frac{1}{1-\phi_{2,C}}\cong 0.44$  (Table 4, Panel A) to  $\sigma_{2,C}=\frac{1}{1-\phi_{2,C}}\cong 0.45$  (see Table 5, Panel A).



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- The elasticity of substitution for noncognitive skills in the early period declines, changing from  $\sigma_{2,N}=\frac{1}{1-\phi_{2,N}}\cong 0.62$  to  $\sigma_{2,N}=\frac{1}{1-\phi_{2,N}}\cong 0.68$  (in Table 5, Panel B).

References

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- The estimated share parameter for late investments in producing noncognitive skills increases from  $\gamma_{2,C,3}\cong 0.07$  to  $\gamma_{2,C,3}\cong 0.10$ .

Introduction

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- When we include an equation for investments, the estimated elasticity of substitution for noncognitive skills increases in late stages, from  $\sigma_{2,N}=\frac{1}{1-\phi_{2,N}}\cong 0.65$  (in Table 4, Panel B) to  $\sigma_{2,N}=\frac{1}{1-\phi_{2,N}}\cong 0.66$  (in Table 5, Panel B).

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- Thus, the estimated elasticities of substitution from the more general procedure show roughly the same pattern as from the procedure that assumes time-invariant heterogeneity.

Introduction

 The general pattern of decreasing substitution possibilities for cognitive skills and increasing substitution possibilities for noncognitive skills is consistent with the literature on the evolution of cognitive and personality traits (see Borghans et al., 2008; Shiner, 1998; Shiner and Caspi, 2003).

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- Noncognitive traits flourish, i.e., more traits are exhibited at later ages of childhood, and there are more possibilities (more margins to invest in) for compensation of disadvantage.
- For a more extensive discussion, see Web Appendix 1.2.



#### A Model Based Only on Cognitive Skills

 Most of the empirical literature on skill production focuses on cognitive skills as the output of family investment (see, e.g., Todd and Wolpin, 2005, 2007, and the references they cite).



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- It is of interest to estimate a more traditional model that ignores noncognitive skills and the synergism between cognitive and noncognitive skills and between investment and noncognitive skills in production.
- Web Appendix Table 14.1 reports estimates of a version of the model in Table 4 (assuming a model with time-invariant heterogeneity) where noncognitive skills are excluded from the analysis.



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- The estimated productivity parameters for investment are substantially higher in both stages of the model reported in Web Appendix Table 14.1, as are the productivity parameters for parental cognitive skills.
- We note in the next section that the policy implications from a cognitive-skill-only model are very different from the policy implications for a model with cognitive and noncognitive skills.



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  - (a) Self-productivity becomes stronger as children become older, for both cognitive and noncognitive skill formation.
  - (b) Complementarity between cognitive skills and investment becomes stronger as children become older. The elasticity of substitution for cognition is *smaller* in second stage production. It is more difficult to compensate for the effects of adverse environments on cognitive endowments at later ages than it is at earlier ages. This pattern of the estimates helps to explain the evidence on ineffective cognitive remediation strategies for disadvantaged adolescents reported in Cunha et al. (2006).

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  - (c) Complementarity between noncognitive skills and investments becomes *weaker* as children become older, but the estimated effects are not that different.

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- The elasticity of substitution between investment and current endowments increases slightly between the first stage and the second stage in the production of noncognitive skills.
- It is somewhat easier at *later* stages of childhood to remediate early disadvantage using investments in noncognitive skills.

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- 16% is due to adolescent cognitive capabilities.
- 12% is due to adolescent noncognitive capabilities.
- Measured parental investments account for 15% of the variation in educational attainment.
- These estimates suggest that the measures of cognitive and noncognitive capabilities that we use are powerful, but not exclusive, determinants of educational attainment and that other factors, besides the measures of family investment that we use, are at work in explaining variation in educational attainment.



 To examine the implications of these estimates, we analyze a standard social planning problem that can be solved solely from knowledge of the technology of skill formation and without knowledge of parental preferences and parental access to lending markets.

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- We determine optimal allocations of investments from a fixed budget to maximize aggregate schooling for a cohort of children.
- We also consider a second social planning problem that minimizes aggregate crime.

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- We do not model parental investment responses to the policy.

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- These simulations produce a measure of the investment that is needed from whatever source to achieve the specified target.

• Suppose that there are H children indexed by  $h \in \{1, ..., H\}$ .

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- Let  $\pi_h$  denote additional unobserved determinants of outcomes.
- Denote  $\theta_{1,h} = (\theta_{C,1,h}, \theta_{N,1,h}, \theta_{C,P,h}, \theta_{N,P,h}, \pi_h)$  and let  $F(\theta_{1,h})$  denote its distribution.

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- The key substitution parameters are basically the same in this model and the more general model with estimates reported in Table 5.
- The price of investment is assumed to be the same in each period.

• The social planner maximizes aggregate human capital subject to a budget constraint B = 2H, so that the per capita budget is 2 units of investments.

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- We draw H children from the initial distribution  $F(\theta_{1,h})$ , and solve the problem of how to allocate finite resources 2H to maximize the average education of the cohort.

• Formally, the social planner maximizes aggregate schooling

$$\max \bar{S} = \frac{1}{H} \sum_{h=1}^{H} S\left(\theta_{C,3,h}, \theta_{N,3,h}, \pi_{h}\right),$$

subject to the aggregate budget constraint,

$$\sum_{h=1}^{H} (I_{1,h} + I_{2,h}) = 2H, \tag{23}$$

the technology constraint,

$$\theta_{k,t+1,h} = f_{k,t} \left( \theta_{C,t,h}, \theta_{N,t,h}, \theta_{C,P,h}, \theta_{N,P,h}, \pi_h \right)$$

for  $k \in \{C, N\}$  and  $t \in \{1, 2\}$ , and the initial endowments of the child and her family.

• We assume no discounting.

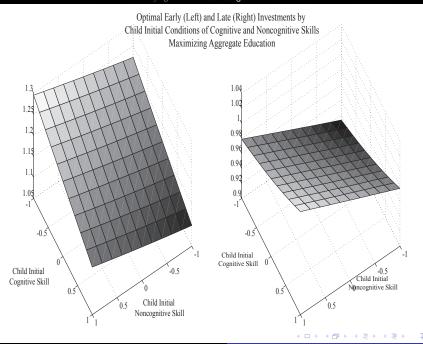
- We assume no discounting.
- Solving this problem, we obtain optimal early and late investments,  $I_{1,h}$  and  $I_{2,h}$ , respectively, for each child h.

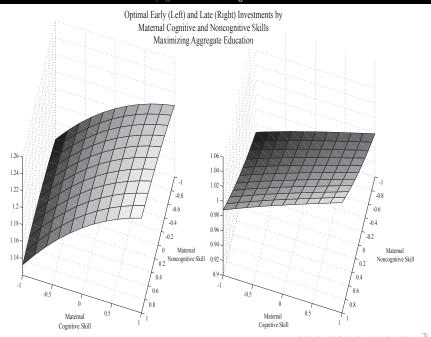
- We assume no discounting.
- Solving this problem, we obtain optimal early and late investments,  $l_{1,h}$  and  $l_{2,h}$ , respectively, for each child h.
- An analogous social planning problem is used to minimize crime.

• Figures 2 (for the child's personal endowments) and 3 (for maternal endowments) show the profiles of early (left hand side graph) and late (right hand side graph) investment as a function of child and maternal endowments.

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- Figures 2 (for the child's personal endowments) and 3 (for maternal endowments) show the profiles of early (left hand side graph) and late (right hand side graph) investment as a function of child and maternal endowments.
- For the most disadvantaged, the optimal policy is to invest a lot in the early years.
- Moon (2010) shows that, in actuality, society and family together invest much more in the early years of the advantaged compared to the disadvantaged.





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- A similar profile emerges for investments to reduce aggregate crime, which for the sake of brevity, we do not display.

 Figures 4 and 5 reveal that the ratio of optimal early-to-late investment as a function of the child's personal endowments declines with advantage whether the social planner seeks to maximize educational attainment (left hand side) or to minimize aggregate crime (right hand side).

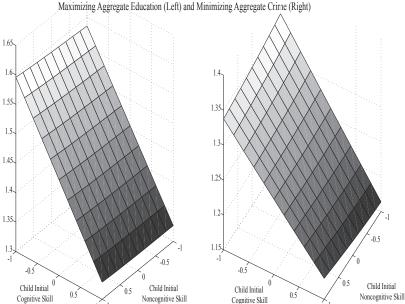
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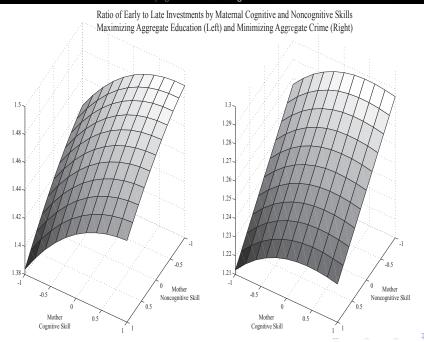
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- A somewhat similar pattern emerges for the optimal ratio of early-to-late investment as a function of maternal endowments with one interesting twist.
- The optimal investment ratio is non-monotonic in the mother's cognitive skill for each level of her noncognitive skills.
- At very low or very high levels of maternal cognitive skills, it is better to invest relatively more in the second period than if her endowment is at the mean.



Ratio of Early to Late Investments by
Child Initial Condtions of Cognitive and Noncognitive Skills





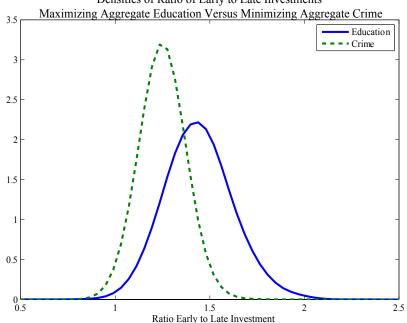


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- Figure 6 plots the density of the ratio of early-to-late investment for education and crime.
- Crime is more intensive in noncognitive skill than educational attainment, which depends much more strongly on cognitive skills.

Densities of Ratio of Early to Late Investments



 Because compensation for adversity in noncognitive skills is somewhat less costly in the second period, and because of discounting of costs and concavity of the technology, it is efficient to invest relatively more in noncognitive traits in the second period.

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- Because compensation for adversity in noncognitive skills is somewhat less costly in the second period, and because of discounting of costs and concavity of the technology, it is efficient to invest relatively more in noncognitive traits in the second period.
- The opposite is true for cognitive skills.
- It is optimal to weight first and second period investments in the directions indicated in the figure.

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- Targeted strategies are likely to be effective especially for different targets that weight cognitive and noncognitive traits differently.

## Some Economic Intuition that Explains the Simulation Results

 This subsection provides an intuition for the simulation results just discussed.

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- Given the (weak) complementarity implicit in technology (3) and (4), how is it possible to obtain our result that it is optimal to invest relatively more in the early years of the most disadvantaged?

## Some Economic Intuition that Explains the Simulation Results

- This subsection provides an intuition for the simulation results just discussed.
- Given the (weak) complementarity implicit in technology (3) and (4), how is it possible to obtain our result that it is optimal to invest relatively more in the early years of the most disadvantaged?
- The answer hinges on the interaction between different measures of disadvantage.

• Consider the following example where individuals have a single capability,  $\theta$ .



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- Suppose that there are two periods for investment, which we denote by periods 1 (early) and 2 (late).
- For each period, there is a different technology that produces skills.

Assume that the technology for period one is:

$$\theta_2 = \gamma_1 \theta_1 + \gamma_2 I_1 + (1 - \gamma_1 - \gamma_2) \theta_P.$$

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For period two it is:

$$\theta_3 = \min \left\{ \theta_2, I_2, \theta_P \right\}.$$

These patterns of complementarity are polar cases that represent, in extreme form, the empirical pattern found for cognitive skill accumulation: that substitution possibilities are greater early in life compared to later in life.

• The problem of society is to choose how much to invest in child A and child B in periods 1 and 2 to maximize total aggregate skills,  $\theta_3^A + \theta_3^B$ , subject to the resource constraint  $I_1^A + I_2^A + I_1^B + I_2^B \leq M$ , where M is total resources available to the family.

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- Formally, the problem is

Introduction

$$\max \left[ \begin{array}{l} \min \left\{ \gamma_{1} \theta_{1}^{A} + \gamma_{2} I_{1}^{A} + \left(1 - \gamma_{1} - \gamma_{2}\right) \theta_{P}^{A}, I_{2}^{A}, \theta_{P}^{A} \right\} + \\ \min \left\{ \gamma_{1} \theta_{1}^{B} + \gamma_{2} I_{1}^{B} + \left(1 - \gamma_{1} - \gamma_{2}\right) \theta_{P}^{B}, I_{2}^{B}, \theta_{P}^{B} \right\} \end{array} \right]$$
subject to:  $I_{1}^{A} + I_{2}^{A} + I_{1}^{B} + I_{2}^{B} \leq M$  (24)

• When the resource constraint (24) does not bind, as it does not if M is above a certain threshold (determined by  $\theta_P$ ), optimal investments are

$$I_1^A = \frac{(\gamma_1 + \gamma_2) \theta_P^A - \gamma_1 \theta_1^A}{\gamma_2}$$
$$I_2^A = \theta_P^A$$

$$I_1^B = \frac{(\gamma_1 + \gamma_2) \theta_P^B - \gamma_1 \theta_1^B}{\gamma_2}$$
$$I_2^B = \theta_P^B$$

• Notice that if child A is disadvantaged compared to B on both measures of disadvantage,  $(\theta_1^A < \theta_1^B)$  and  $\theta_A^P < \theta_B^P$ , it can happen that

$$I_1^A > I_1^B$$
, but  $I_2^A < I_2^B$ 

if

$$\theta_P^A - \theta_P^B > \frac{\gamma_1}{\gamma_1 + \gamma_2} \left( \theta_1^A - \theta_1^B \right).$$

• Notice that if child A is disadvantaged compared to B on both measures of disadvantage,  $(\theta_1^A < \theta_1^B)$  and  $\theta_A^P < \theta_B^P$ , it can happen that

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if

$$\theta_P^A - \theta_P^B > \frac{\gamma_1}{\gamma_1 + \gamma_2} \left( \theta_1^A - \theta_1^B \right).$$

• Thus, if parental endowments are less negative than the childhood endowments (scaled by  $\frac{\gamma_1}{\gamma_1+\gamma_2}$ ), it is optimal to invest more in the early years for the disadvantaged and less in the later years.

• Notice that since  $(1 - \gamma_1 - \gamma_2) = \gamma_P$  is the productivity parameter on  $\theta_P$  in the first period technology, we can rewrite this condition as  $(\theta_P^A - \theta_P^B) > \frac{\gamma_1}{1 - \gamma_P} (\theta_1^A - \theta_1^B)$ .

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- The higher the self-productivity  $(\gamma_1)$  and the higher the parental environment productivity,  $\gamma_P$ , the more likely will this inequality be satisfied for any fixed level of disparity.

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# Implications of a One Cognitive Skill Model

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- This is the traditional focus in the analysis of educational production functions.
- See, e.g., Todd and Wolpin, 2003, 2007 and Hanushek and Woessmann, 2008.
- The optimal policy is to invest relatively more in the early years of the initially advantaged.
- Our estimates of two-stage and one-stage models based solely on cognitive skills would indicate that it is optimal to perpetuate initial inequality, and not to invest relatively more in disadvantaged young children.

#### Conclusion

 This paper formulates and estimates a multistage model of the evolution of children's cognitive and noncognitive skills as determined by parental investments at different stages of the life cycle of children.

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- We estimate the elasticity of substitution between contemporaneous investment and stocks of skills inherited from previous periods to determine the substitutability between early and late investments.
- We also determine the quantitative importance of early endowments and later investments in determining schooling attainment.



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- We establish nonparametric identification of a wide class of nonlinear factor models which enable us to determine the technology of skill formation.
- We present an analysis of the identification of production technologies with endogenous missing inputs that is more general than the replacement function analysis of Olley and Pakes (1996) and allows for measurement error in the proxy variables.

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- We develop a nonparametric approach to this problem by anchoring test scores in adult outcomes with interpretable scales.

 Using measures of parental investment and children's outcomes from the Children of the National Longitudinal Survey of Youth, we estimate the parameters governing the substitutability between early and late investments in cognitive and noncognitive skills.

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- These estimates are consistent with evidence reported in Cunha et al. (2006).

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- The optimal investment strategy to maximize aggregate schooling attainment is to target the most disadvantaged at younger ages.
- The optimal strategy favors later investment over early investment if the goal is to reduce crime.



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- An empirical model that ignores the impact of noncognitive skills on productivity and outcomes yields the opposite conclusion that an optimal policy would perpetuate initial advantages.